

Autoencoders for Collaborative Filtering

WSDM 2020 paper "RecVAE: A New Variational Autoencoder for Top-N Recommendations with Implicit Feedback"

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Background: Collaborative filtering

- ▶ Linear models
 - ▶ user-item collaborative filtering:
 - ▶ probabilistic matrix factorization (PMF) [Salakhutdinov and Mnih, 2008]
 - ▶ weighted matrix factorization (WMF) [Hu et al., 2008]
 - ▶ item-item collaborative filtering:
 - ▶ sparse linear methods (SLIM) [Ning and Karypis, 2011]
 - ▶ embarrassingly shallow autoencoders (EASE) [Steck, 2019]

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 - ▶ embarrassingly shallow autoencoders (EASE) [Steck, 2019]
- ▶ Deep learning-based models
 - ▶ autoencoder-based:
 - ▶ AutoRec [Sedhain et al., 2015]
 - ▶ collaborative denoising autoencoder (CDAE) [Wu et al., 2016]
 - ▶ multinomial VAE (Mult-VAE) [Liang et al., 2018]
 - ▶ ranking-critical training (RaCT) [Lobel et al., 2019]
 - ▶ ...

Background: SLIM

- ▶ Sparse Linear Methods (SLIM) [Ning and Karypis, 2011]:

$$\arg \min_W \frac{1}{2} \|R - RW\|_F^2 + \frac{\beta}{2} \|W\|_F^2 + \lambda \|W\|_1$$

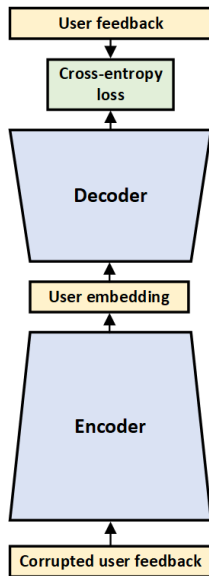
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- ▶ subject to $\text{diag}(W) = 0$

Background: Autoencoders for Collaborative Filtering



$$\tilde{\mathbf{x}}_u = \text{noise}(\mathbf{x}_u),$$

$$\tilde{\mathbf{z}}_u = \text{encoder}(\tilde{\mathbf{x}}_u),$$

$$\tilde{\mathbf{x}}_u^{\text{pred}} = \text{decoder}(\tilde{\mathbf{z}}_u),$$

where \mathbf{x}_u is a user feedback vector with $x_{ui} = 1$ iff the u th user has positively interacted with the i th item

Background: Variational Autoencoders

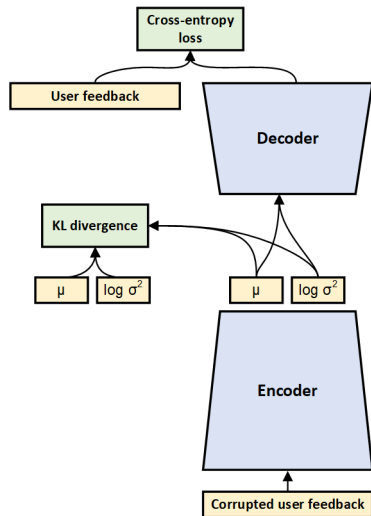
- ▶ Variational autoencoders (VAE) [Kingma and Welling, 2013]:

$$\begin{aligned}\log p(\mathbf{x}) &= \log \int p(\mathbf{x}|\mathbf{z})p(\mathbf{z})d\mathbf{z} = \\ &= \mathbb{E}_{q(\mathbf{z}|\mathbf{x})} \log \frac{p(\mathbf{z}, \mathbf{x})}{q(\mathbf{z}|\mathbf{x})} + \text{KL}(q(\mathbf{z}|\mathbf{x})\|p(\mathbf{z}|\mathbf{x})) \geq \\ &\geq \text{ELBO} = \mathbb{E}_{q(\mathbf{z}|\mathbf{x})} \log p(\mathbf{x}|\mathbf{z}) - \text{KL}(q(\mathbf{z}|\mathbf{x})\|p(\mathbf{z}))\end{aligned}$$

Background: Variational Autoencoders for Collaborative Filtering

- ▶ Multinomial VAE (Mult-VAE) [Liang et al., 2018]:
 - ▶ partially regularized VAE with multinomial likelihood:

$$\mathcal{L} = \mathbb{E}_{q_{\phi}(\mathbf{z}_u | \mathbf{x}_u)} \log \text{Mult}(\mathbf{x}_u | \pi(\mathbf{z}_u)) - \beta \text{KL}(q_{\phi}(\mathbf{z}_u | \mathbf{x}_u) || p(\mathbf{z}_u))$$



Our model

- ▶ Most works that develop further developments of VAE for collaborative filtering introduce alternative loss functions:
 - ▶ Wasserstein autoencoders (aWAE) [Zhong and Zhang, 2018]
 - ▶ ranking-critical training (RaCT) [Lobel et al., 2019]
 - ▶ negative-binomial VAE (NBVAE) [Zhao et al., 2019]
- ▶ Instead, we propose several new regularization techniques for Mult-VAE

Background: Variational Autoencoder with Arbitrary Conditioning

- ▶ Variational Autoencoder with Arbitrary Conditioning (VAEAC) [Ivanov et al., 2018]:

$$\begin{aligned} \log p_{\theta,b}(\mathbf{x}_b | \mathbf{x}_{1-b}, b) &\geq \\ \mathcal{L}_{VAEAC} &= \mathbb{E}_{q_{\phi}(\mathbf{z} | \mathbf{x}, b)} \log p_{\theta}(\mathbf{x}_b | \mathbf{z}, \mathbf{x}_{1-b}, b) - \\ &\quad - \text{KL}(q_{\phi}(\mathbf{z} | \mathbf{x}, b) \| p_{\theta}(\mathbf{z} | \mathbf{x}_{1-b}, b)); \quad (1) \end{aligned}$$

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- ▶ We combine them together as a conditional prior:

$$\tilde{p}(\mathbf{z}|\phi_{old}, \mathbf{x}) = \alpha \mathcal{N}(\mathbf{z}|0, \mathbf{I}) + (1 - \alpha) q_{\phi_{old}}(\mathbf{z}|\mathbf{x})$$

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- ▶ This improves both stability and performance
- ▶ Serves as an auxiliary loss function

Background: Trust Region Policy Optimization

$$\begin{aligned} & \underset{\theta}{\text{maximize}} \mathbb{E}_{s \sim \rho_{\theta_{\text{old}}}, a \sim q} \left[\frac{\pi_{\theta}(a|s)}{q(a|s)} Q_{\theta_{\text{old}}}(s, a) \right] \\ & \text{subject to } \mathbb{E}_{s \sim \rho_{\theta_{\text{old}}}} \text{KL}(\pi_{\theta_{\text{old}}}(\cdot|s) \parallel \pi_{\theta}(\cdot|s)) \leq \delta. \end{aligned}$$

Rescaling KL-divergence

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- ▶ We denote by \mathbf{X}_u^o the set of items that the u th user likes according to the training set and by \mathbf{X}_u^f the set of items that the u th user actually likes
- ▶ Then we can derive that \mathcal{L} can be approximated with

$$\mathbb{E}_{q_\phi(\mathbf{z}_u|\mathbf{x}_u)} \log \text{Mult}(\mathbf{x}_u|\boldsymbol{\pi}(\mathbf{z}_u)) - \frac{|\mathbf{X}_u^o|}{|\mathbf{X}_u^f|} \text{KL}(q_\phi(\mathbf{z}_u|\mathbf{x}_u)||p(\mathbf{z}_u)),$$

where $|\mathbf{X}_u^f|$ is unknown, so we let it be equal to some constant

Rescaling KL-divergence

$$\begin{aligned}
 \mathcal{L} &= \mathbb{E}_{q_\phi(z_u|x_u^f)} \log \text{Mult}(\mathbf{x}_u^f | \boldsymbol{\pi}(z_u)) - \text{KL} \left(q_\phi(z_u|x_u^f) \parallel p(z_u) \right) = \\
 &\sum_{a \in \mathbf{X}_u^f} \mathbb{E}_{q_\phi(z_u|x_u^f)} \log \text{Cat}(\mathbf{1}_a | \boldsymbol{\pi}(z_u)) - \text{KL} \left(q_\phi(z_u|x_u^f) \parallel p(z_u) \right) + C_u = \\
 &\sum_{a \in \mathbf{X}_u^f} \left[\mathbb{E}_{q_\phi(z_u|x_u^f)} \log \text{Cat}(\mathbf{1}_a | \boldsymbol{\pi}(z_u)) - \frac{1}{|\mathbf{X}_u^f|} \text{KL} \left(q_\phi(z_u|x_u^f) \parallel p(z_u) \right) \right] + C_u \approx \\
 &\frac{|\mathbf{X}_u^f|}{|\mathbf{X}_u^o|} \sum_{a \in \mathbf{X}_u^o} \left[\mathbb{E}_{q_\phi(z_u|x_u^f)} \log \text{Cat}(\mathbf{1}_a | \boldsymbol{\pi}(z_u)) - \frac{1}{|\mathbf{X}_u^f|} \text{KL} \left(q_\phi(z_u|x_u^f) \parallel p(z_u) \right) \right] + C'_u \approx \\
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 &\frac{|\mathbf{X}_u^f|}{|\mathbf{X}_u^o|} \left[\mathbb{E}_{q_\phi(z_u|x_u)} \sum_{a \in \mathbf{X}_u^o} \log \text{Cat}(\mathbf{1}_a | \boldsymbol{\pi}(z_u)) - \frac{|\mathbf{X}_u^o|}{|\mathbf{X}_u^f|} \text{KL} \left(q_\phi(z_u|x_u) \parallel p(z_u) \right) \right] + C'_u = \\
 &\frac{|\mathbf{X}_u^f|}{|\mathbf{X}_u^o|} \left[\mathbb{E}_{q_\phi(z_u|x_u)} \log \text{Mult}(\mathbf{x}_u | \boldsymbol{\pi}(z_u)) - \frac{|\mathbf{X}_u^o|}{|\mathbf{X}_u^f|} \text{KL} \left(q_\phi(z_u|x_u) \parallel p(z_u) \right) \right] + C''_u
 \end{aligned} \tag{2}$$

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- ▶ Updated architecture
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Complementary improvements

- ▶ Updated architecture
 - ▶ Deep encoder
 - ▶ Linear decoder (item embeddings matrix + bias vector)
- ▶ Alternating Training
 - ▶ Encoder and decoder are trained alternately
 - ▶ More iterations are required to train the encoder
- ▶ Regularization by denoising
 - ▶ It appears that the decoder is overregularized
 - ▶ Therefore, we do not use denoising during decoder training

Results

	ML-20M	Netflix	MSD
WMF [Hu et al., 2008]	0.386	0.351	0.257
Mult-VAE [Liang et al., 2018]	0.426	0.386	0.316
RaCT [Lobel et al., 2019]	<u>0.434</u>	0.392	0.319
EASE [Steck, 2019]	0.420	<u>0.393</u>	0.389
RecVAE (ours)	0.442	0.394	<u>0.326</u>

- ▶ NDCG@100 scores, best results highlighted in bold, second best ones underlined

Conclusion

- ▶ We have proposed several improvements for Mult-VAE
- ▶ Combined together, they significantly improve the performance, making RecVAE the new state of the art in deep learning-based autoencoders for collaborative filtering

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