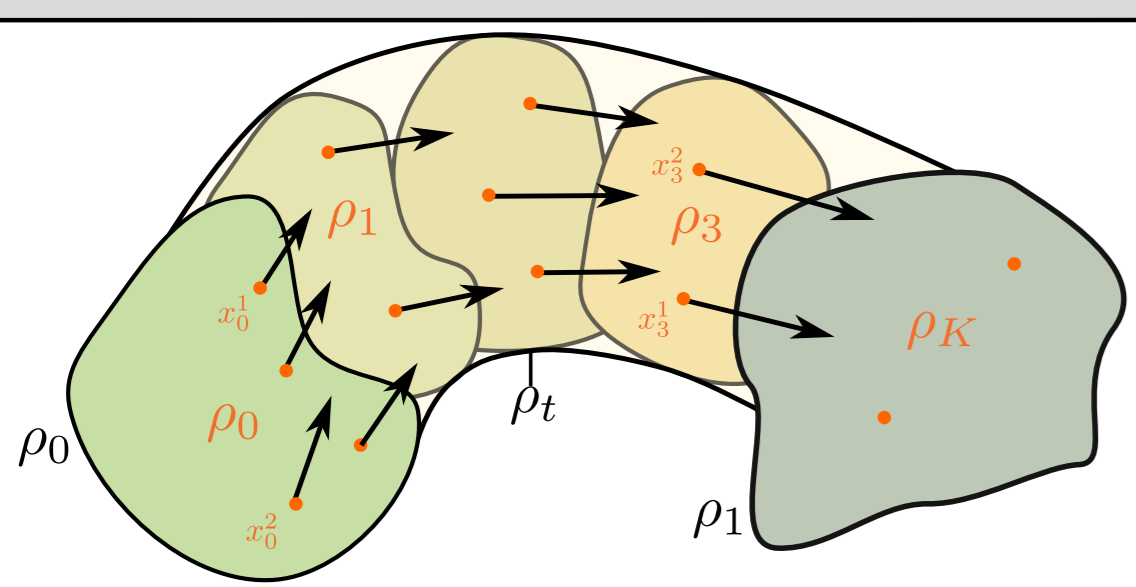
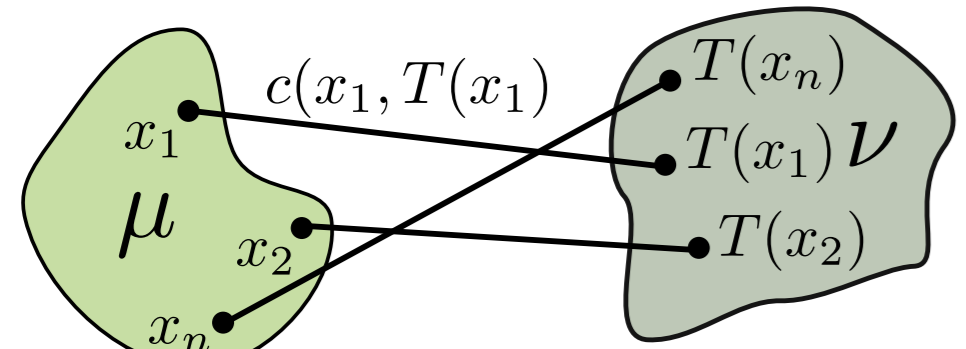
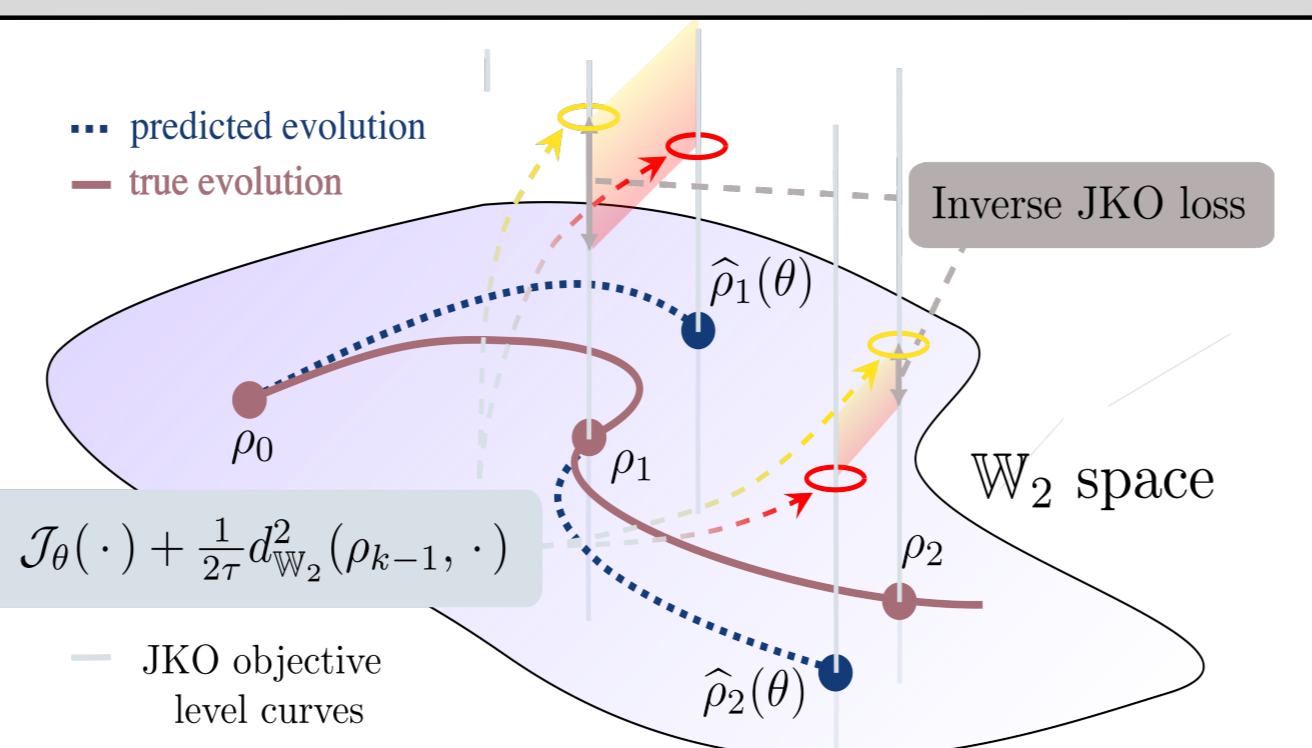
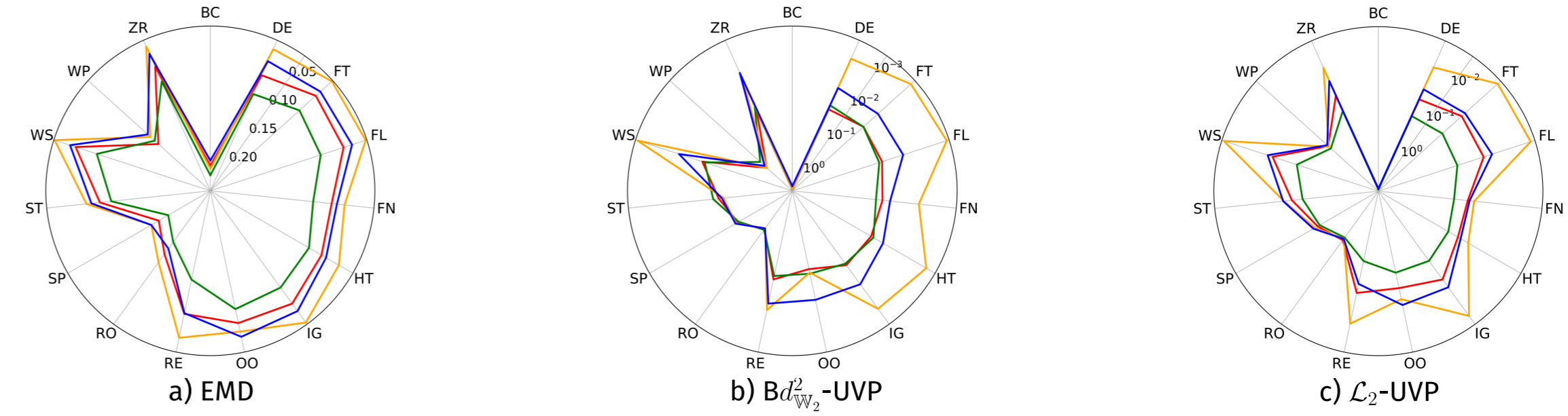
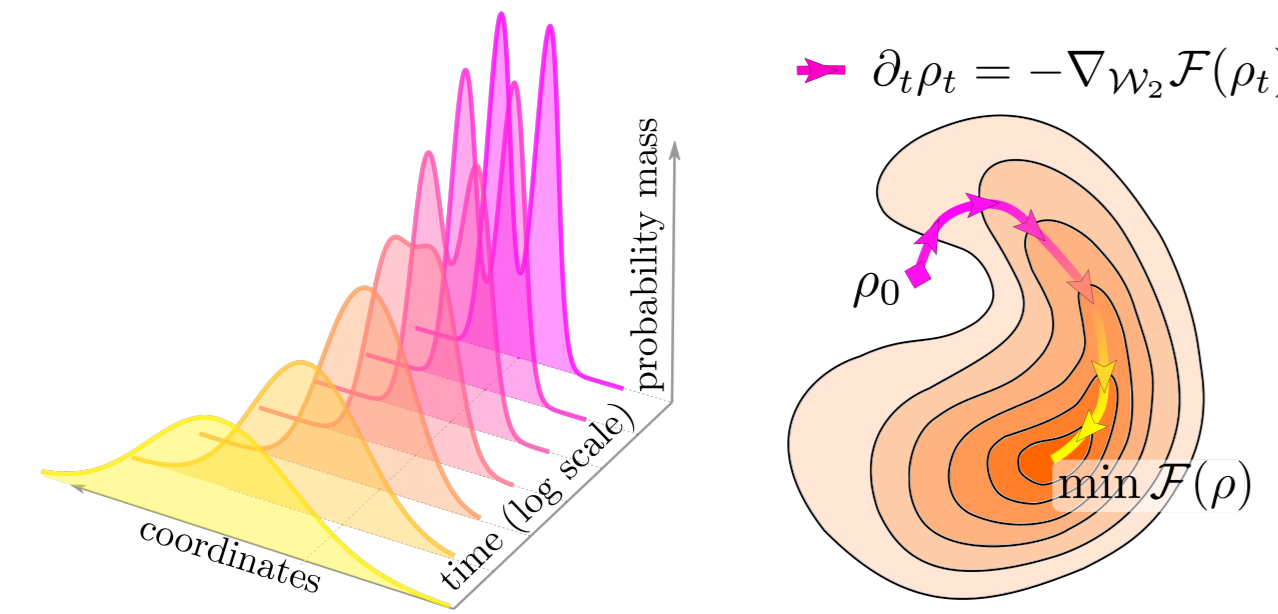




Learning of Population Dynamics: Inverse Optimization Meets JKO Scheme

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Evgeny Burnaev^{1,3} Alexander Korotin^{1,3}

Problem Statement	The JKO Scheme	Theoretical Aspects	Single-Cell Data																											
<div></div> <p>We are given independent samples from marginals $\{\rho_k\}_{k=0}^K$ of the evolving distribution ρ_t at corresponding time points $t_0 < t_1 < \dots < t_K$. Importantly, each distribution ρ_k may be represented by a different number of samples.</p>	<p>Jordan, Kinderlehrer, and Otto extended the idea of <i>implicit Euler scheme</i> to the space of probability measures, introducing a variational time discretization of the Fokker-Planck equation (5), now known as the <i>JKO scheme</i>:</p> $\rho_{k+1}^\tau = \arg \min_{\rho \in \mathcal{P}(\mathcal{X})} \left\{ \mathcal{J}(\rho) + \frac{1}{2\tau} d_{\mathbb{W}_2}^2(\rho, \rho_k^\tau) \right\} = \text{JKO}_{\tau\mathcal{J}}(\rho_k^\tau), \quad \rho_0^\tau = \rho_0$ <p>where $\tau > 0$ is the time step. As $\tau \rightarrow 0$, the sequence $\rho_k^\tau, k \in \mathbb{N}$ converges to the continuous solution ρ_t of (4), which motivates our assumption that the ground truth sequence of measures $\{\rho_k\}_{k=0}^K$ follows $\rho_{k+1} = \text{JKO}_{\Delta t_k \mathcal{J}^*}(\rho_k)$.</p>	<p>Theorem (Quality bounds for recovered potential energy). Let $\varepsilon(V) \doteq \mathcal{L}(V^*, T_{V^*}) - \mathcal{L}(V, T_V)$ be the gap between the optimal and optimized value of inverse JKO loss with internal \min_T problem solved exactly, i.e., $T_V \doteq \min_T \mathcal{L}(V, T)$. Let \mathcal{X} be a convex set; (modified) potentials $V_q \doteq \tau V + \frac{1}{2} \ \cdot\ _2^2 : \mathcal{X} \rightarrow \mathbb{R}$ be strictly convex and $\frac{1}{\beta}$-smooth. Then there exists $C = C(\tau, \beta)$ such that following inequality holds:</p> $\int_{\mathcal{X}} \ \nabla V^*(y) - \nabla V(y)\ ^2 d\rho_1(y) \leq C\varepsilon(V).$	<p>Setup: We perform experiments using a leave-two-out setup. Since the EB dataset contains five timesteps, we remove the second (t_2) and fourth (t_4) timesteps, and then evaluate how well our method can reconstruct the data from the remaining t_1 and t_3 timesteps.</p> <table><thead><tr><th>Method</th><th>t_2</th><th>t_4</th></tr></thead><tbody><tr><td>Vanilla-SB</td><td>1.49 ± 0.063</td><td>1.55 ± 0.034</td></tr><tr><td>DMSB</td><td>1.13 ± 0.082</td><td>1.45 ± 0.16</td></tr><tr><td>TrajectoryNet</td><td>2.03 ± 0.04</td><td>1.93 ± 0.08</td></tr><tr><td>MMSB</td><td>1.27 ± 0.028</td><td>1.57 ± 0.048</td></tr><tr><td>JKOnet[*]</td><td>1.145 ± 0.033</td><td>2.529 ± 0.014</td></tr><tr><td>ijKOnet_V (Ours)</td><td>1.082 ± 0.011</td><td>1.147 ± 0.001</td></tr><tr><td>JKOnet[*]_{t,V}</td><td>4.414 ± 1.499</td><td>2.771 ± 0.197</td></tr><tr><td>ijKOnet_{t,V} (Ours)</td><td>0.983 ± 0.037</td><td>0.849 ± 0.021</td></tr></tbody></table> <p>5D experiment. \mathbb{W}_2 distance (↓) comparison across t_2 and t_4.</p>	Method	t_2	t_4	Vanilla-SB	1.49 ± 0.063	1.55 ± 0.034	DMSB	1.13 ± 0.082	1.45 ± 0.16	TrajectoryNet	2.03 ± 0.04	1.93 ± 0.08	MMSB	1.27 ± 0.028	1.57 ± 0.048	JKOnet [*]	1.145 ± 0.033	2.529 ± 0.014	ijKOnet _V (Ours)	1.082 ± 0.011	1.147 ± 0.001	JKOnet [*] _{t,V}	4.414 ± 1.499	2.771 ± 0.197	ijKOnet _{t,V} (Ours)	0.983 ± 0.037	0.849 ± 0.021
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<div></div> <p>The (squared) <i>Wasserstein-2 distance</i> $d_{\mathbb{W}_2}$ between two a.c. probability measures $\mu, \nu \in \mathcal{P}_{ac}(\mathcal{X})$ is defined as:</p> $d_{\mathbb{W}_2}^2(\mu, \nu) = \min_{T: T\# \mu = \nu} \int_{\mathcal{X}} \ x - T(x)\ _2^2 d\mu(x), \quad (1)$ <p>where the optimal map T^* is known as the <i>Monge map</i>.</p>	<div></div> <p>Thanks to assumption $\rho_{k+1} = \text{JKO}_{\tau\mathcal{J}^*}(\rho_k)$, we can derive an inequality that becomes an equality if a candidate functional \mathcal{J} matches the ground truth functional \mathcal{J}^*:</p> $\min_{\rho} \left\{ \mathcal{J}(\rho) + \frac{1}{2\tau} d_{\mathbb{W}_2}^2(\rho_k, \rho) \right\} \leq \mathcal{J}(\rho_{k+1}) + \frac{1}{2\tau} d_{\mathbb{W}_2}^2(\rho_k, \rho_{k+1}). \quad (8)$ <p>Moving the right-hand side to the left yields an expression that is always upper-bounded by zero, regardless of the choice of \mathcal{J}. Maximizing the resulting gap, we obtain loss:</p> $\max_{\mathcal{J}} \min_{T^k} \sum_{k=0}^{K-1} \left[\mathcal{J}(T^k\# \rho_k) - \mathcal{J}(\rho_{k+1}) + \frac{1}{2\tau} \int_{\mathcal{X}} \ x - T^k(x)\ _2^2 d\rho_k(x) dx \right].$	<p>Goal: Evaluate how our method learns potentials in the unpaired setup, i.e., particle trajectories are resampled across time steps, resulting in temporally uncorrelated samples, demonstrating hardness of the corrected setup.</p> <div></div> <p>Goal: Demonstrate how our method learns potentials in the paired setup, i.e., particle trajectories are preserved across time steps, resulting in temporally correlated samples, enabling a direct visual comparison with JKOnet[*].</p>																												
Wasserstein Gradient Flows	Related JKO-based Methods																													
<div></div> <p>For an energy functional $\mathcal{F} : \mathcal{P}(\mathcal{X}) \rightarrow \mathbb{R}$, the gradient flow in $\mathbb{W}_2(\mathcal{X})$, called the <i>Wasserstein gradient flow (WGF)</i>, is an absolutely continuous curve $\rho_t : \mathbb{R}_+ \rightarrow \mathcal{P}(\mathcal{X})$ starting at ρ_0 that follows the steepest descent direction of \mathcal{F}:</p> $\partial_t \rho_t = -\nabla_{\mathbb{W}_2} \mathcal{F}(\rho_t), \quad \rho_{(t=0)} = \rho_0, \quad (2)$ <p>where $\nabla_{\mathbb{W}_2} \mathcal{F}(\rho_t)$ denotes the <i>Wasserstein gradient</i> in \mathbb{W}_2. It can be rewritten in the form of the <i>continuity equation</i>, expressing mass conservation under the velocity field v_t:</p> $\partial_t \rho_t + \nabla \cdot (\rho_t v_t) = 0, \quad v_t = -\nabla \frac{\delta \mathcal{F}}{\delta \rho}(\rho_t). \quad (3)$	<p>JKOnet formulates the task of population dynamics recovery as a bi-level optimization problem aimed at minimizing the discrepancy between observed distributions ρ_k and model predictions $\hat{\rho}_k$:</p> $\mathcal{L}_{\text{JKOnet}}(\theta, \varphi) = \sum_{k=0}^{K-1} d_{\mathbb{W}_2}^2(\hat{\rho}_k, \rho_k), \quad \text{s.t. } \hat{\rho}_0 = \rho_0, \quad \hat{\rho}_{k+1} = \nabla \psi_k^* \# \hat{\rho}_k$ $\psi_k^* \doteq \arg \min_{\varphi: \psi_\varphi \in \text{CVX}} \mathcal{J}_\theta(\nabla \psi_\varphi \# \hat{\rho}_k) + \frac{1}{2\tau} \int_{\mathcal{X}} \ x - \nabla \psi_\varphi(x)\ ^2 d\hat{\rho}_k$ <p>where CVX denotes the set of continuously differentiable convex functions from \mathcal{X} to \mathbb{R}.</p> <p>JKOnet[*] addresses the limitations of the original JKOnet by replacing the full JKO optimization problem with its first-order optimality conditions. The method minimizes the following objective, utilizing a <i>precomputed</i> optimal transport plans π_k between ρ_k and ρ_{k+1}:</p> $\mathcal{L}_{\text{JKOnet}^*}(\theta) = \sum_{k=0}^{K-1} \int_{\mathcal{X} \times \mathcal{X}} \left\ \nabla V_{\theta_1}(x_{k+1}) + \int_{\mathcal{X}} \nabla U_{\theta_2}(x_{k+1} - y_{k+1}) d\rho_{k+1}(y_{k+1}) + \theta_3 \frac{\nabla \rho_{k+1}(x_{k+1})}{\rho_{k+1}(x_{k+1})} + \frac{1}{\tau} (x_{k+1} - x_k) \right\ ^2 d\pi_k(x_k, x_{k+1}).$																													
Examples of PDEs as WGFs	<p>Consider the <i>free energy</i> functional:</p> $\mathcal{J}_{\text{FE}}(\rho) = \underbrace{\int_{\mathcal{X}} V(x) d\rho(x)}_{\mathcal{V}(\rho)} + \underbrace{\int_{\mathcal{X} \times \mathcal{X}} W(x - y) d\rho(x) d\rho(y)}_{\mathcal{W}(\rho)} + \underbrace{\int_{\mathcal{X}} U(\rho(x)) dx}_{\mathcal{U}(\rho)}$ <p>where \mathcal{V}, \mathcal{W}, and \mathcal{U} correspond to the system's <i>potential</i>, <i>interaction</i>, and <i>internal</i> energies, respectively. When the energy is $\mathcal{J}_{\text{FP}}(\rho) = \mathcal{V}(\rho) - \beta \mathcal{H}(\rho)$, the resulting PDE is the <i>Fokker-Planck equation</i> with diffusion coefficient β:</p> $\partial_t \rho_t = \nabla \cdot (\nabla V(x) \rho_t) + \beta \nabla^2 \rho_t, \quad (4)$ <p>which is equivalent to the following <i>Itô SDE</i>:</p> $dX_t = -\nabla V(X_t) dt + \sqrt{2\beta} dW_t. \quad (5)$																													