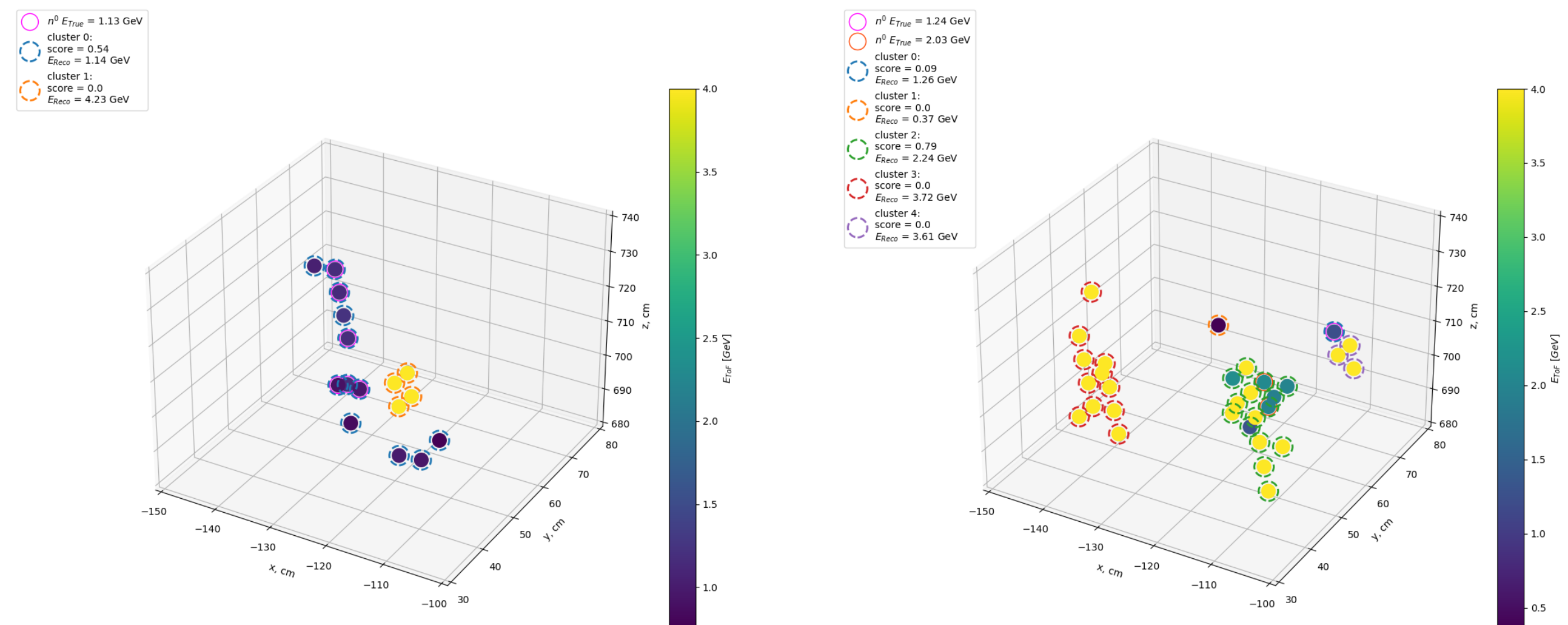


# GNN-based neutron reconstruction in the highly-granular neutron detector at the BM@N experiment

Vladimir Bocharnikov

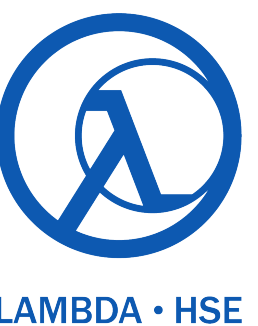
29.10.2025



HSE



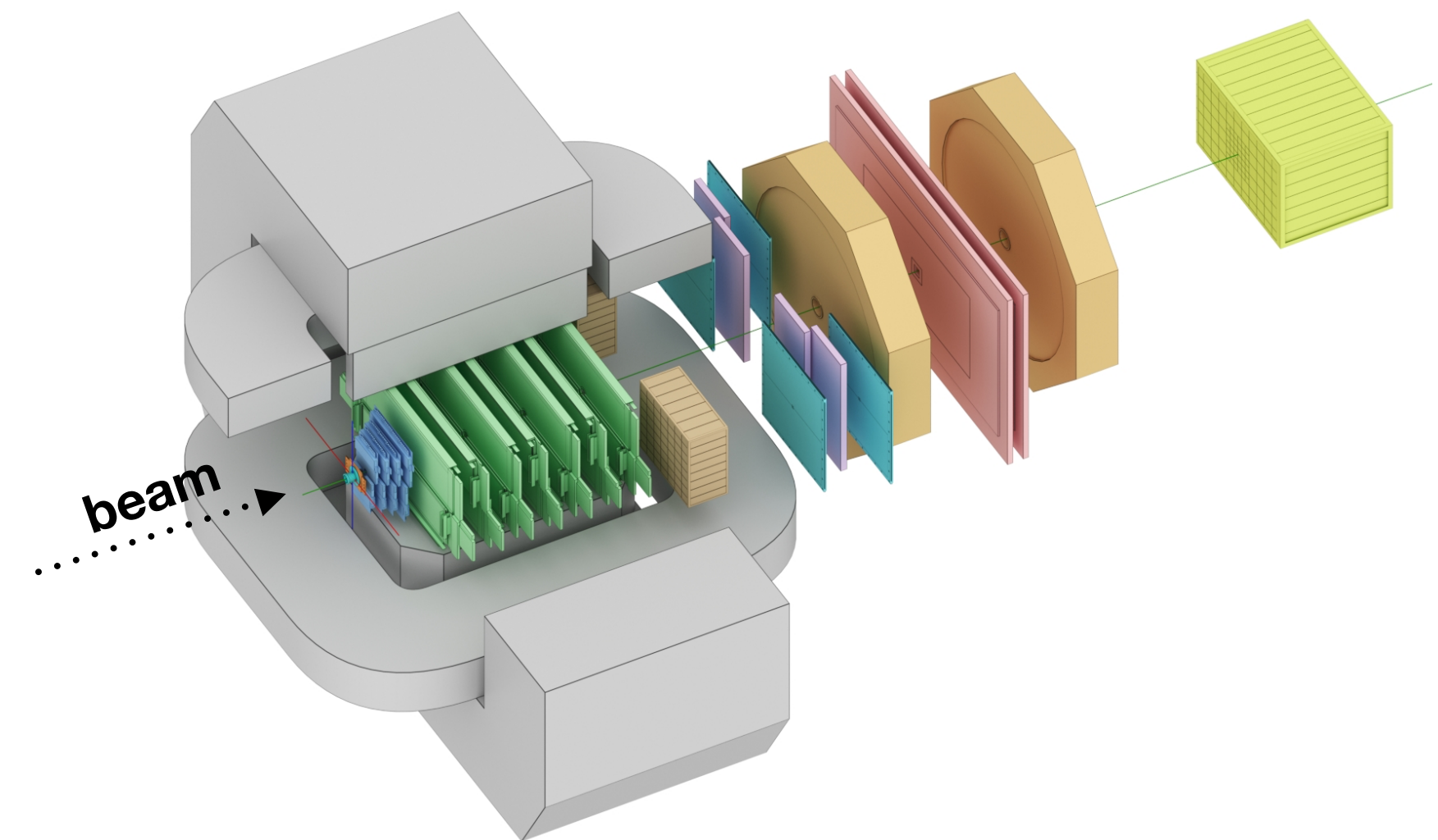
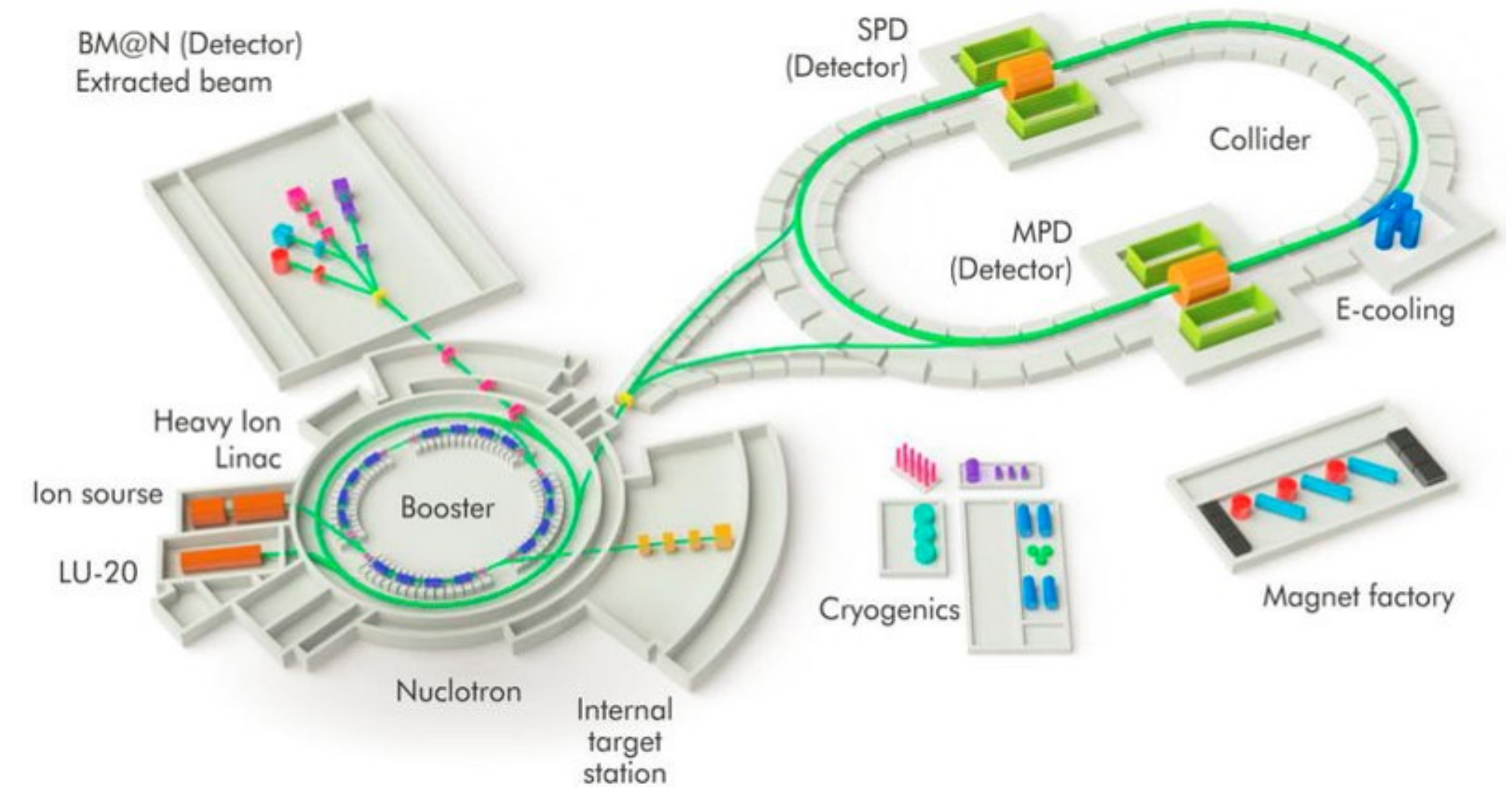
FCS



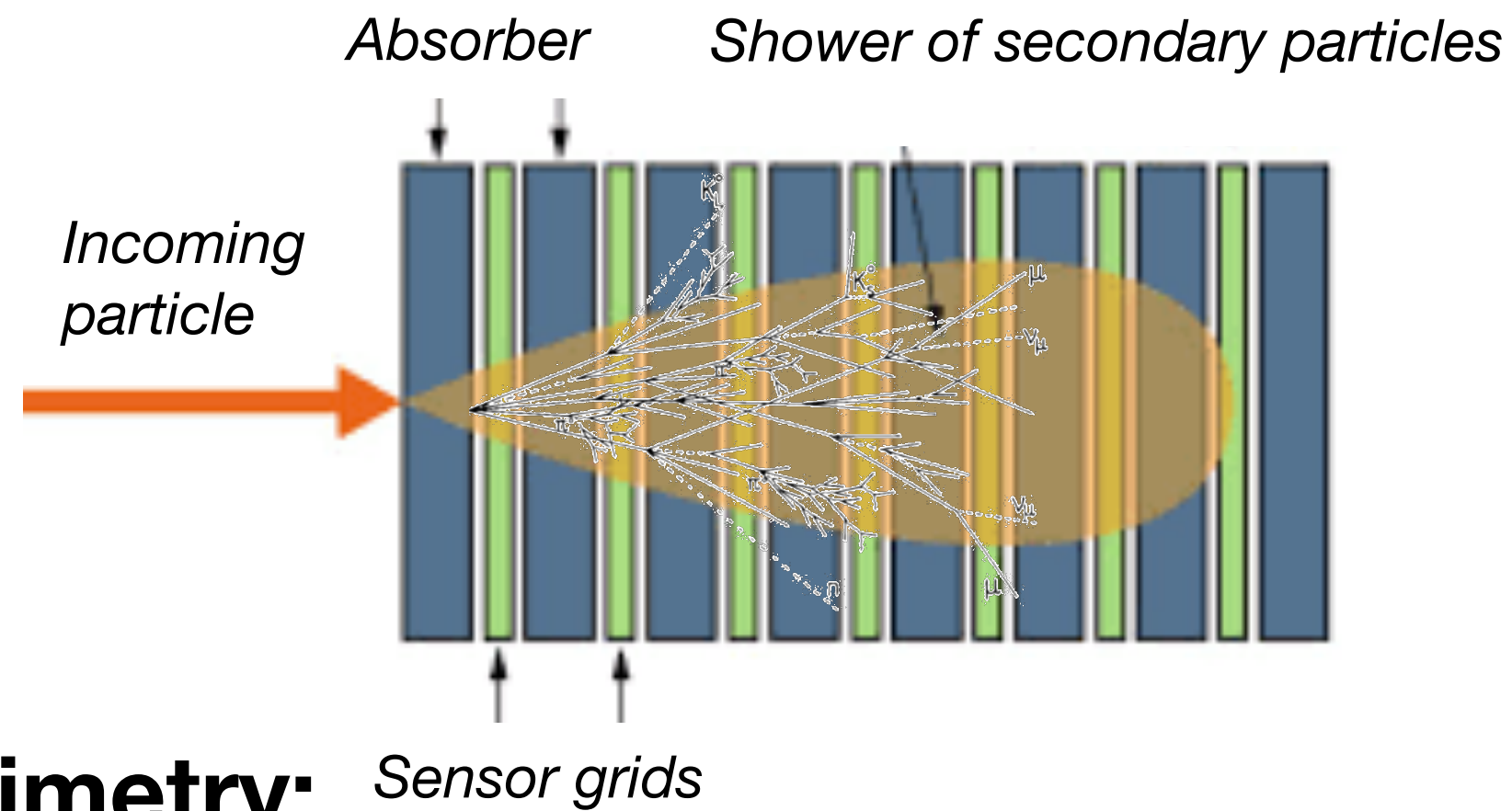
# BM@N experiment

Studies of **Baryonic Matter at the Nuclotron** (NICA, JINR Dubna)

- Heavy-Ion beam with energies up to 4A GeV interacts with fixed target
- ➔ investigate the **equation-of-state (EOS)** of **dense nuclear matter** which plays a central role for the dynamics of core collapse supernovae and for the stability of neutron stars.
- Azimuthal properties of produced particles - important tool for EOS studies
  - we focus on **neutron** flow and yields



# Neutron detection



## Calorimetry:

- Particles interact with matter
- Depends on particle type
  - Neutrons travel on a long distance w/o interaction before producing a shower
- Energy loss transferred to detectable signal
  - Light (e.g. scintillator) -> electric signal
  - Signal collected and acquired
  - *Good energy resolution for 5+ GeV  $n^0$*
- In the end: digitized signal
  - Coordinates, energy deposition, time

## Time-of-Flight (ToF) measurements:

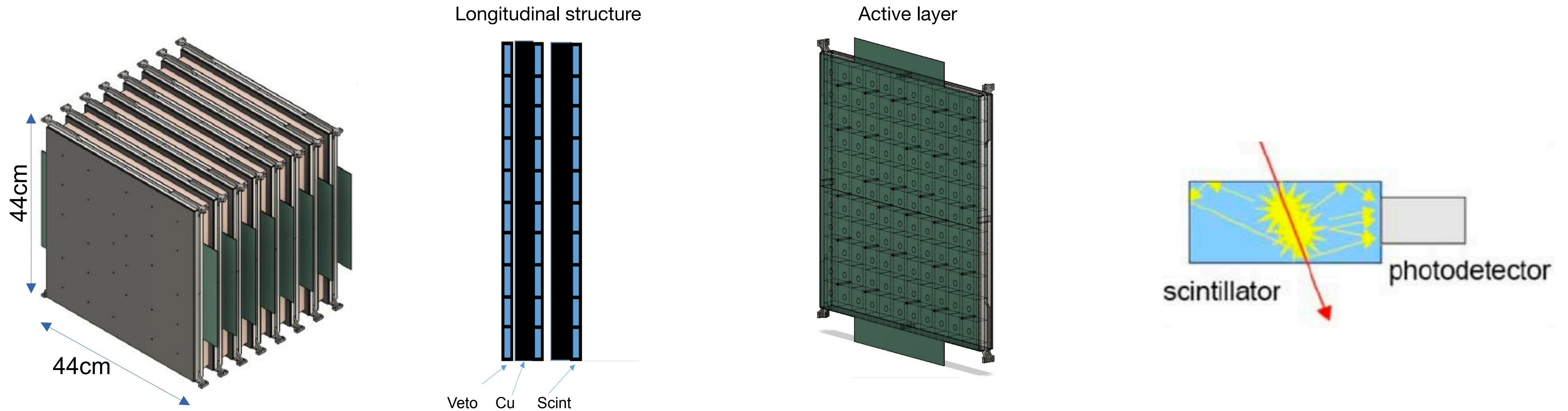
- Time of arrival and distance to the production point gives momentum of a particle
- ➔ With known particle mass (neutron) we can calculate it's energy

$$E_{ToF} = m_n \left( \frac{1}{\sqrt{1 - \left(\frac{v}{c}\right)^2}} - 1 \right) \quad \text{Good energy resolution up to } 2\text{-}3 \text{ GeV } n^0$$

**we use calorimeter image to identify neutron and ToF to reconstruct it's energy**

Neutron is one of the most challenging particle types for reconstruction due to relatively low probability to interact with matter. Yield of visible energy is very low at energies  $< 1\text{ GeV}$

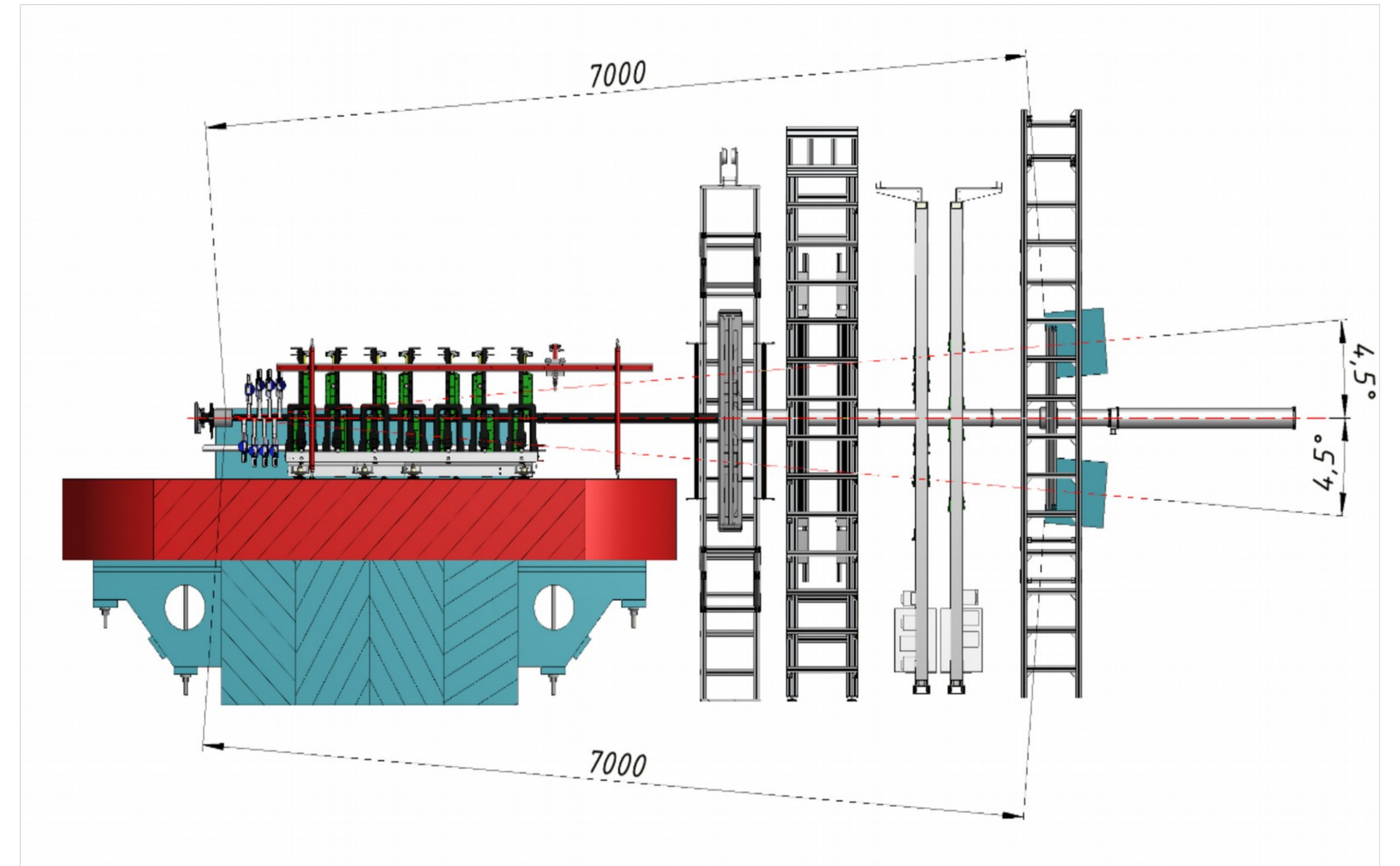
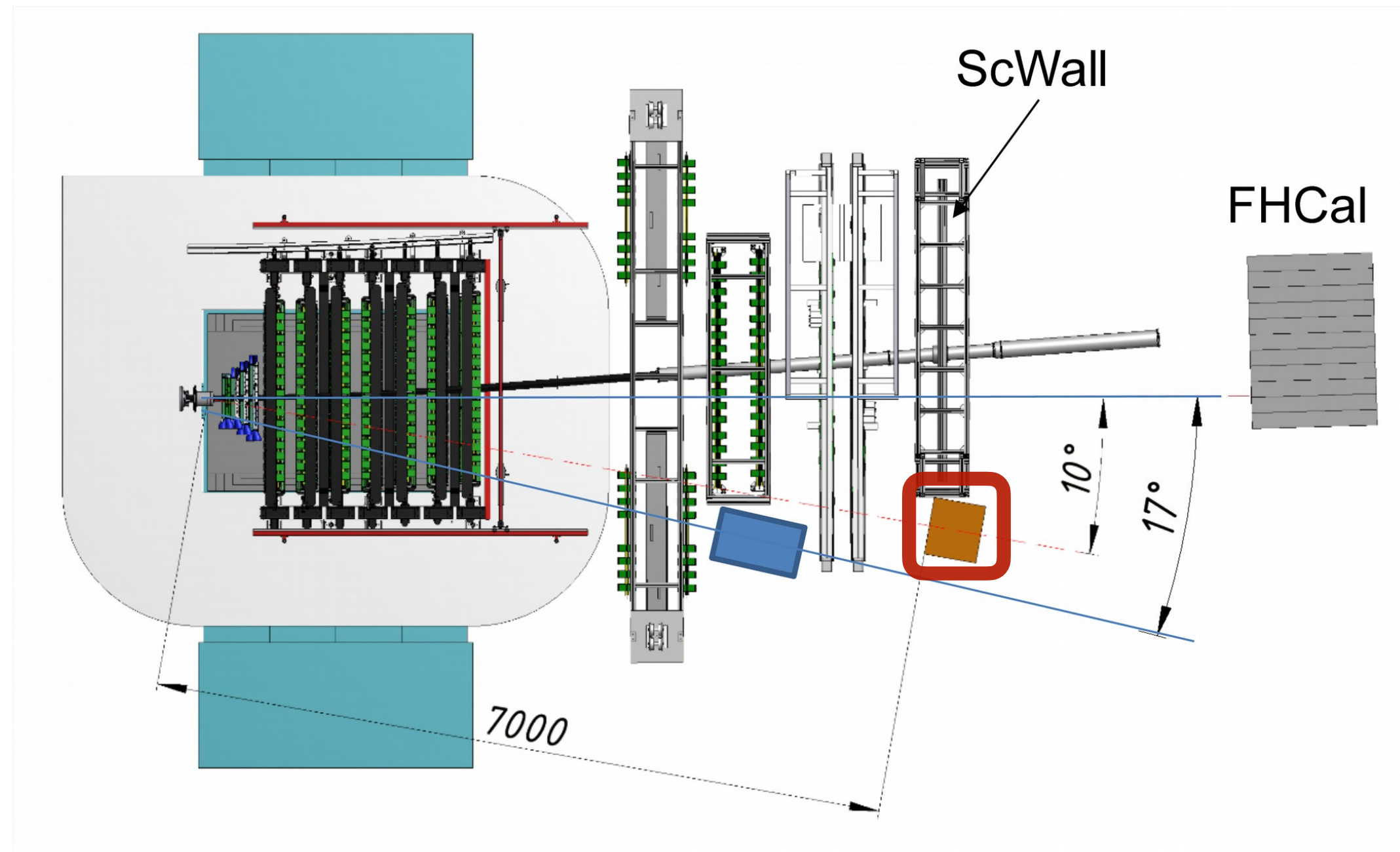
# Highly granular time-of-flight neutron detector (HGND)



- (2x) 8 layers: 3cm Cu (*absorber*) + 2.5cm Scintillator + 0.5cm PCB; 1st layer — ‘veto’ before absorber
  - ➡ Total length: ~0.5m, ~1.5  $\lambda_{in}$
  - ➡ neutron detection efficiency ~60% @ 1 GeV
- Transverse size: **44x44 cm<sup>2</sup>**
- 11x11 scintillator cell grid

- scintillator cells:
  - size: 4x4x2.5 cm<sup>3</sup>,
  - **total number of cells: 968 (x2)**
  - individual readout by SiPM
  - expected time resolution per cell: ~150 ps

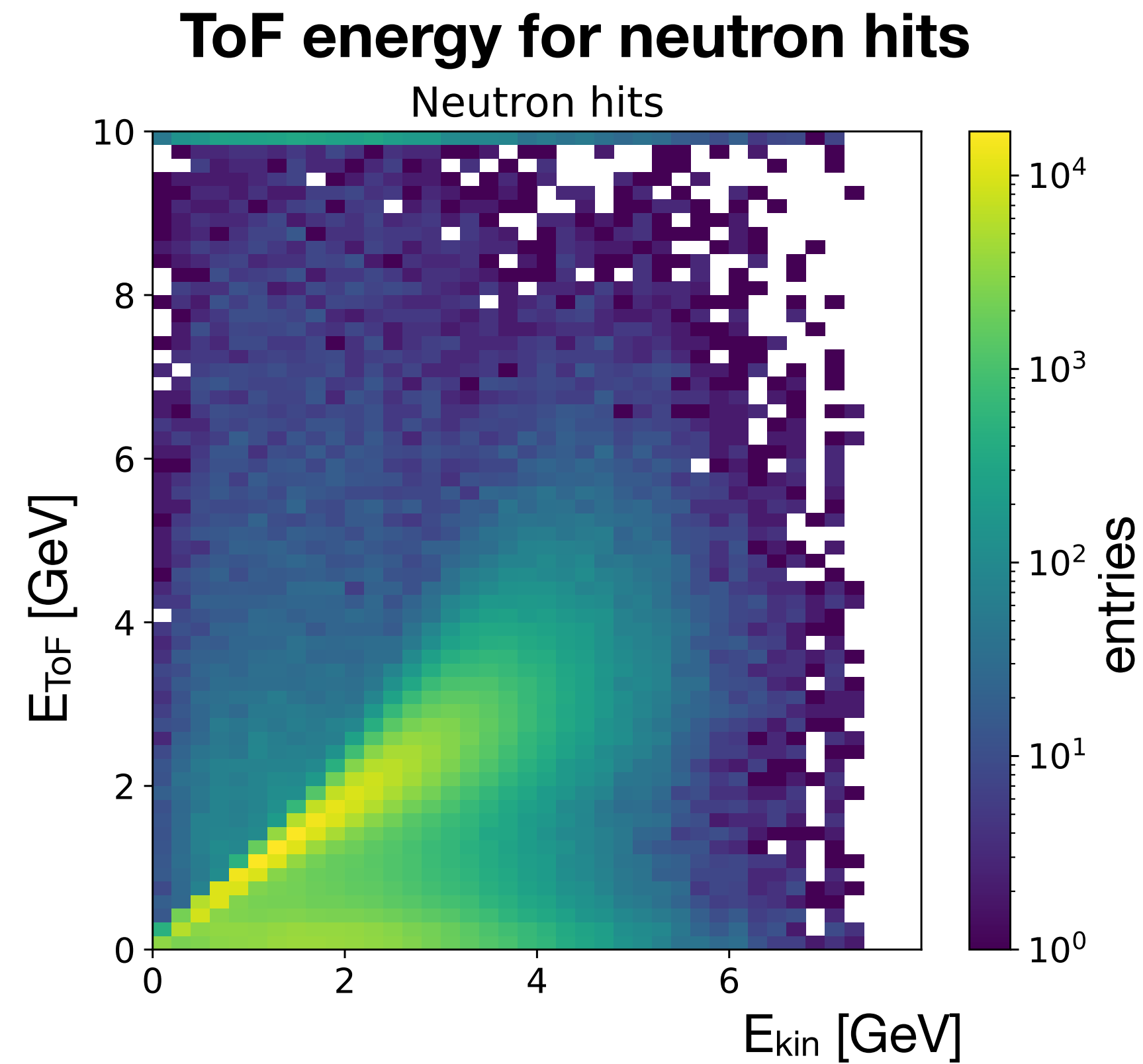
# Detector Setup and Simulations



- HGND sub-detectors are located at  **$10^\circ$  to the beam axis** at  **$\sim 7\text{m}$  from the target**
- Monte-Carlo event simulations with full detector setup model:
  - **3 AGeV Bi+Bi** DCM-QGSM-SMM model + Geant4 v11.2.0 FTFP\_BERT
  - **$\sim 1\text{M}$  events**

# Hit Level Information

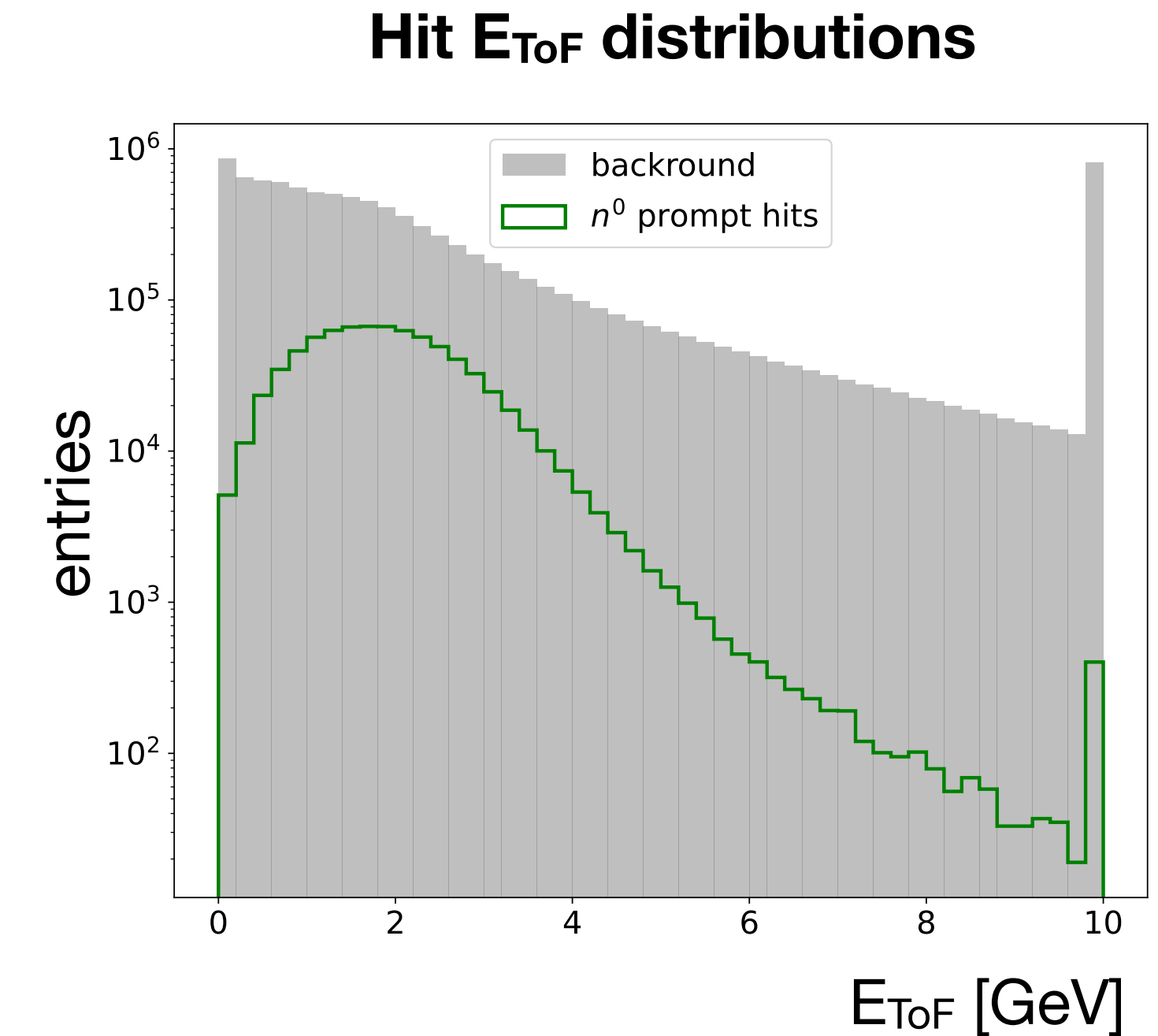
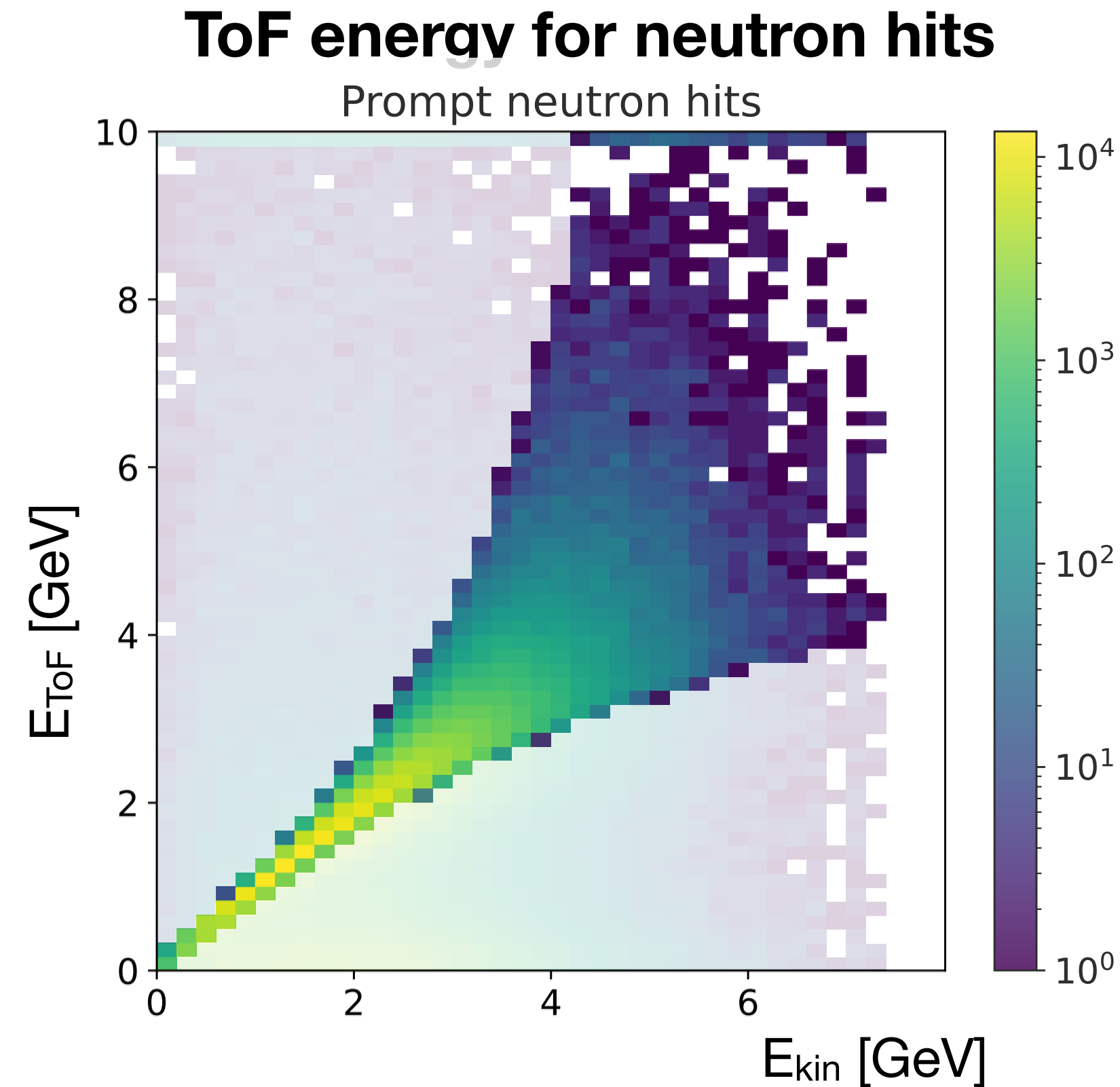
- $E_{\text{dep}} > 3 \text{ MeV} \sim 0.5 \text{ MIP}$
- **ToF energy** for  $n^0$  hypothesis:
$$E_{\text{ToF}} = m_n \left( \frac{1}{\sqrt{1 - \beta^2}} - 1 \right)$$
  - $t_{\text{hit}} + \mathcal{N}(0, \sigma_t = 150 \text{ ps})$
  - clip at 10 GeV
- Each hit is linked with corresponding surface MC particle
- signal — neutrons passed the upstream HGND surface



- Underestimation - neutron shower development
- Overestimation - background contributions in the same hits
  - ➡ More precise labelling is under development

# Hit Level Information

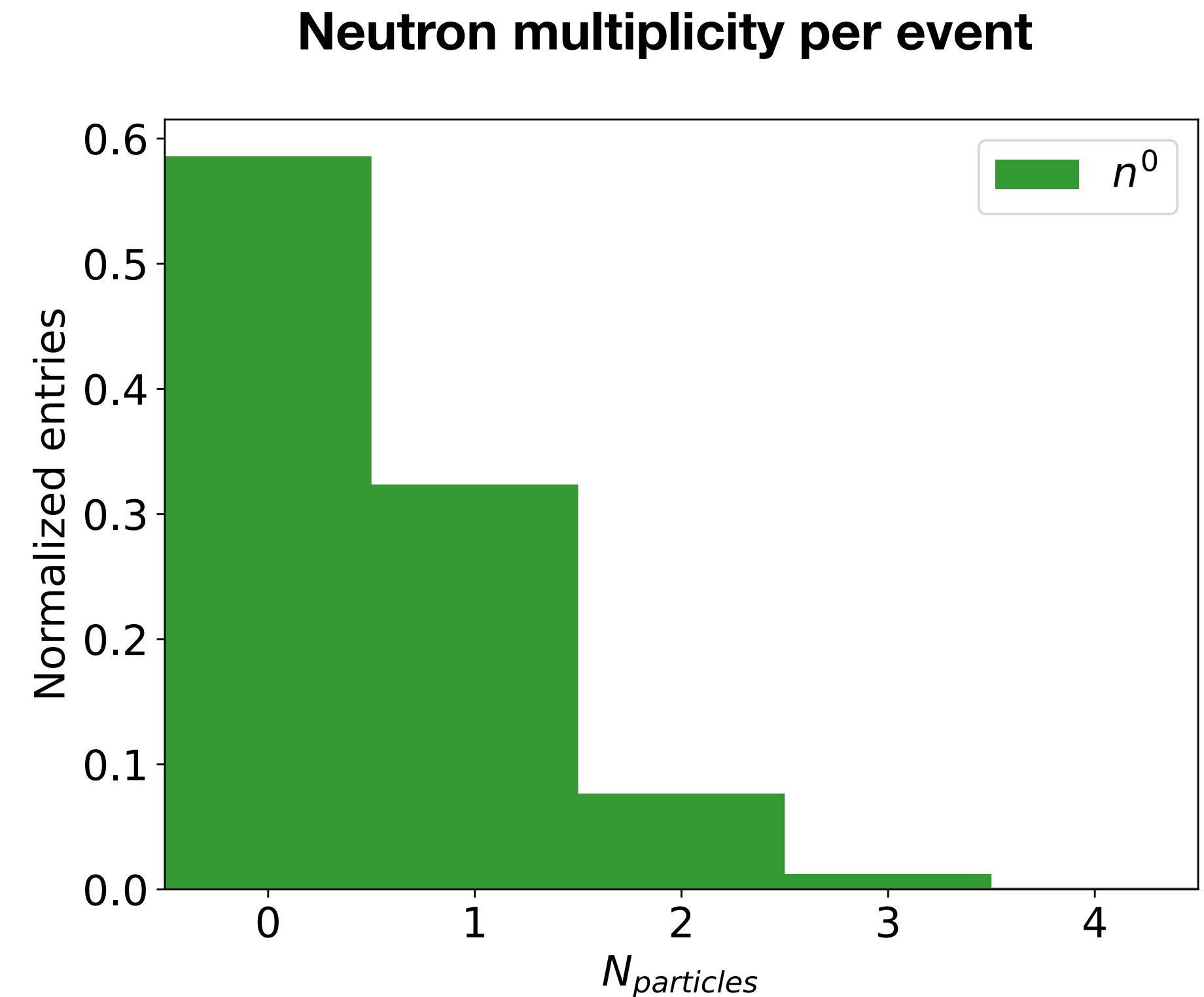
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  - $t_{\text{hit}} + \mathcal{N}(0, \sigma_t = 150 \text{ ps})$
  - clip at 10 GeV
- Each hit is linked with corresponding surface MC particle
- signal — neutrons passed the upstream HGND surface
- **Prompt neutron deposition** selected by  $\mathbf{E}_n \in \mathbf{E}_{\text{ToF}}(t_{\text{hit}} \pm 2\sigma_t)$ 
  - other hits - background



- Underestimation - neutron shower development
- Overestimation - background contributions in the same hits
- ➡ More precise labelling is under development

# Neutron Multiplicity

- Multiplicity counts require
  - existence of **prompt hit**
  - $E_{n0} > 0.1$  GeV
  - neutron passed upstream HGND surface
- Distributions normalised to number of events with energy deposition
  - ➡ Neutron detection efficiency is not discussed
- Reconstruction algorithm has to deal with neutron multiplicities  $> 1$



# Graph Neural Networks (GNN)

## Why Graph Neural Networks:

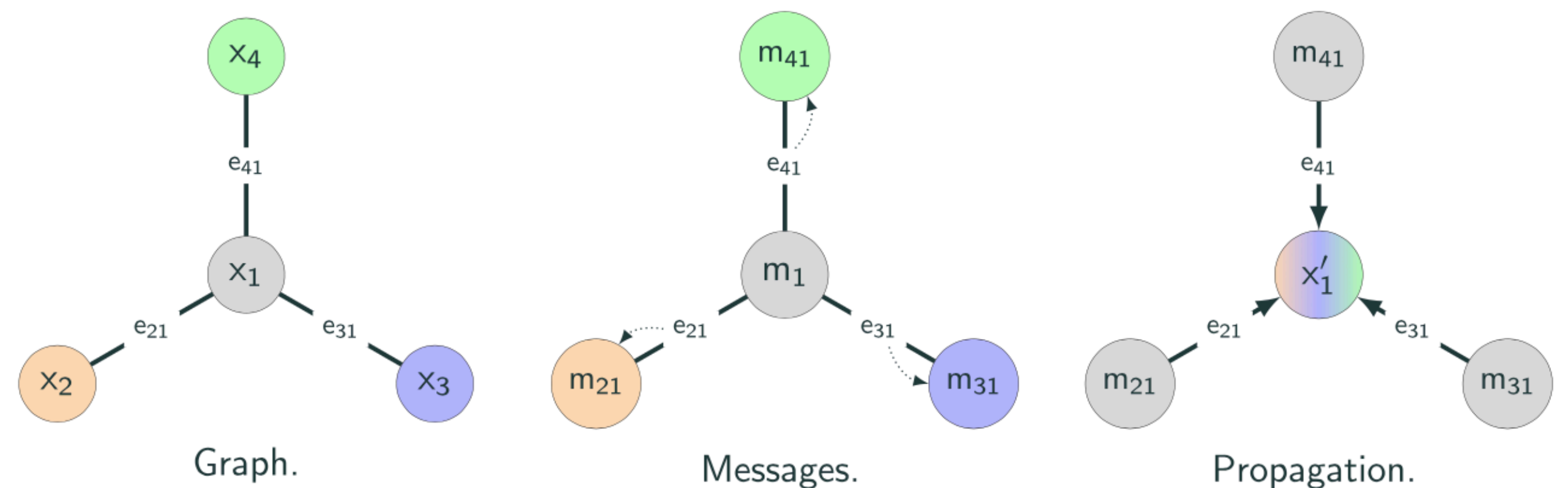
- Natural vector event representation
  - Detector cell hits as graph nodes
- Easily applied to sparse data with variable input size
  - Typically we have signal only in small fraction of sensors
- Captures event structures
- Increasing number of successful implementations in HEP

HEPML-LivingReview

## Message passing architecture

Key idea:

- Edges propagate information between nodes in a trainable manner to encode local graph structures
- Node embeddings are then aggregated to a problem-specific value, e.g.:
  - Graph/hit class “probability” — signal/background
  - Target value — neutron energy



J. Gilmer *et al.*, “Neural message passing for quantum chemistry,” 2017.

# Graph Construction

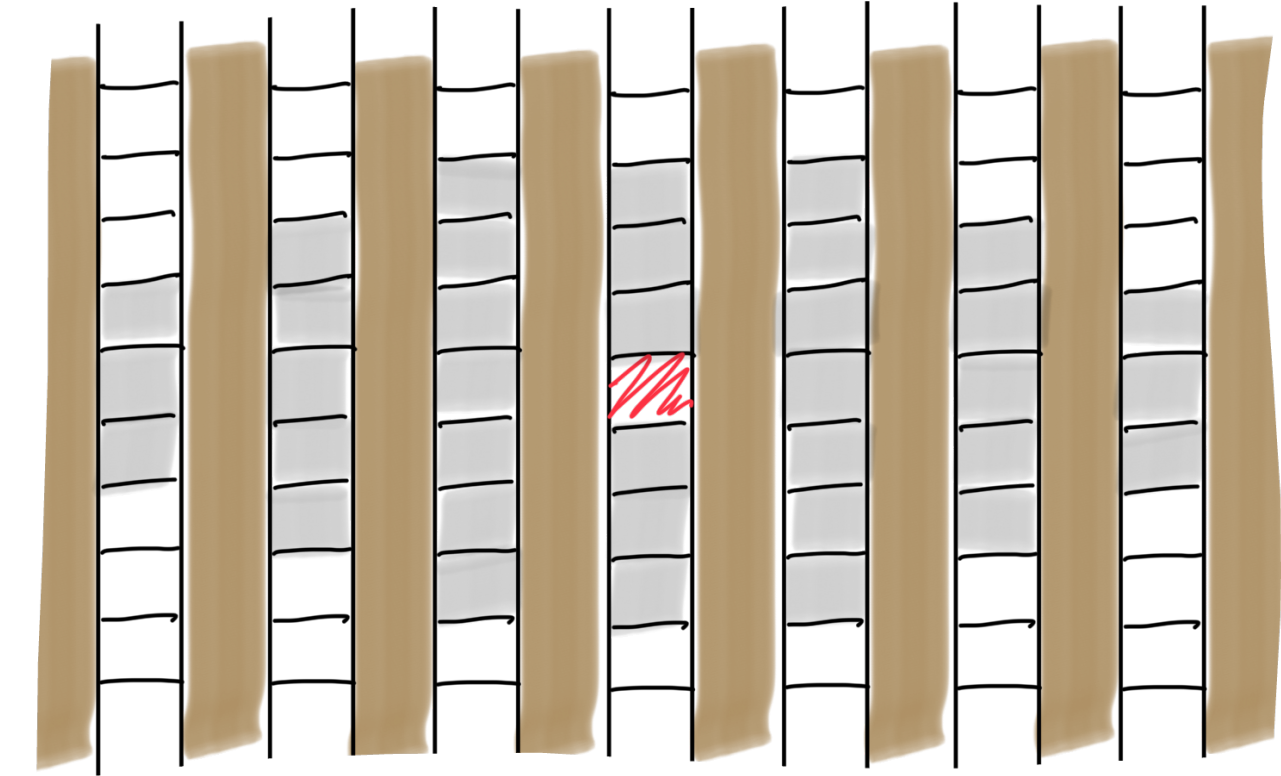
- **Nodes — hits.** Observables per hit:
  - hit coordinates: layer, row, column
  - $E_{\text{dep}} > 3 \text{ MeV} \sim 0.5 \text{ MIP}$
  - hit time +  $\mathcal{N}(0, \sigma = 150\text{ps})$
  - $E_{\text{ToF}}$
- **Edges**
  - Predefined clustering:
    - radius graph.  **$R = 3.6 \text{ cells}$**
    - time window  **$1.5 \text{ ns}$**
    - cluster — **isolated subgraph**

## Labeling for further training

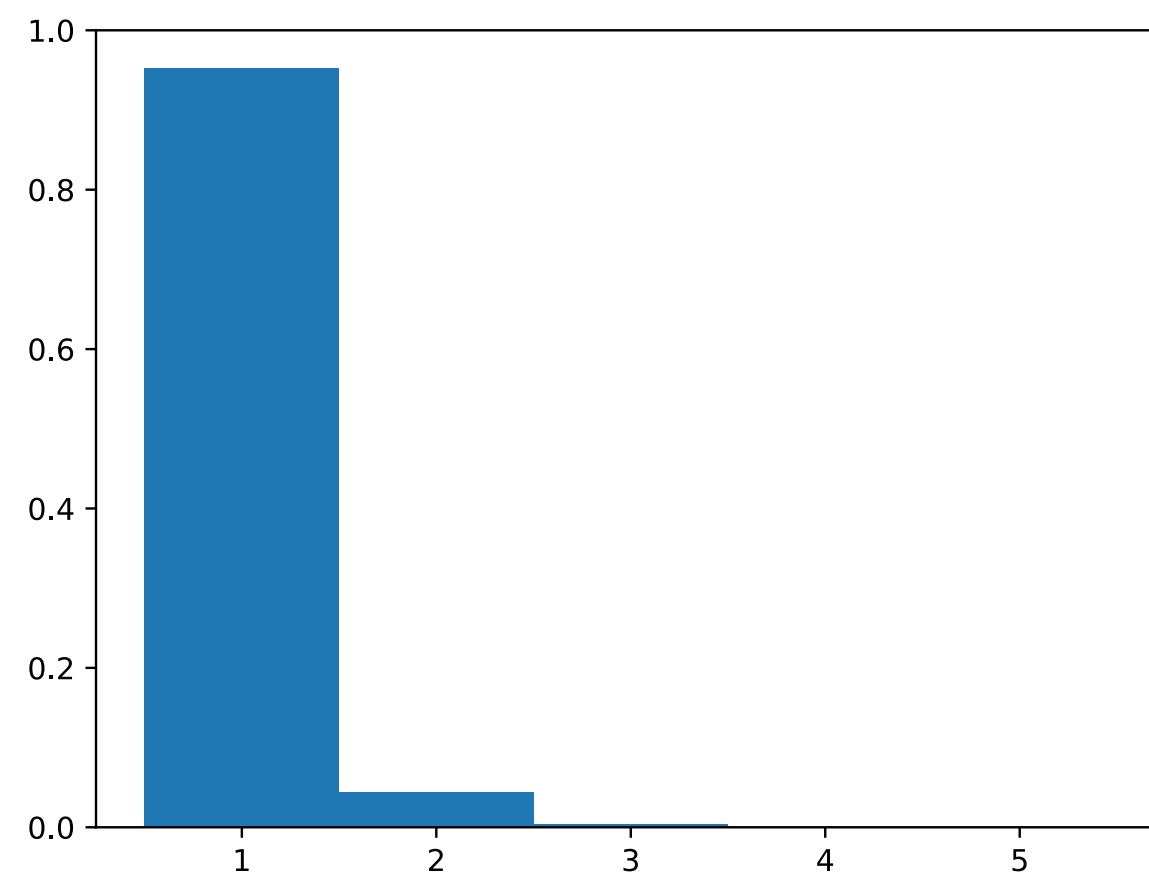
- Cluster level:
  - **Signal** cluster contains at least 1 **prompt neutron** hit
  - **Energy** of fastest neutron with prompt hit in a cluster

# Clustering

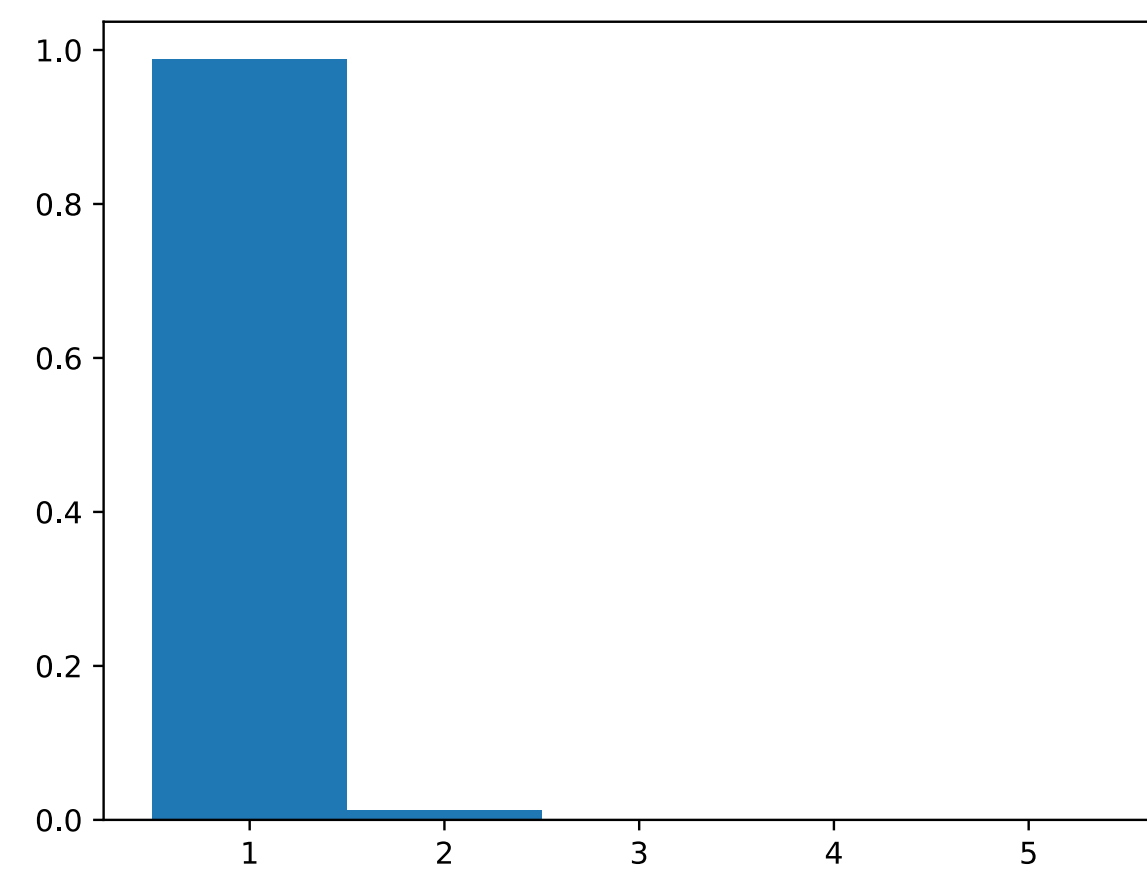
- Soft spatial rule.
    - search radius  **$R = 3.6$  cells**
  - ~strict temporal rule
    - time window  **$1.5$  ns**
- ➡ first guess parameters, to be optimised, included in GNN



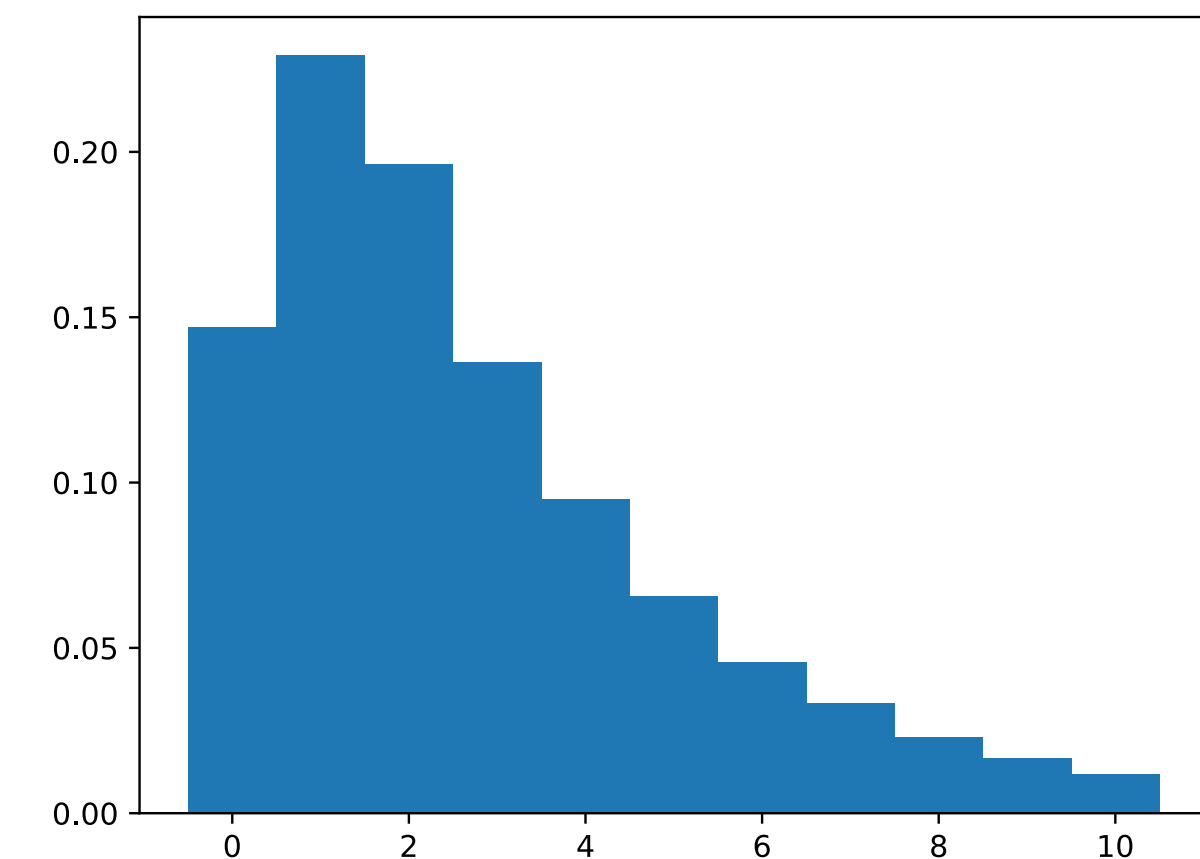
Prompt  $n^0$  multiplicity per signal cluster



Cluster multiplicity per prompt  $n^0$



Background multiplicity per signal cluster



- isolation  $>95\%$
- prompt  $n^0$  splits in secondary clusters at level of  $< 2\%$
- significant background contribution => make use of ML

# GNN Model

## Training objective

- **Cluster level:**
  - predict **neutron class** score
  - reconstruct expected **neutron energy**

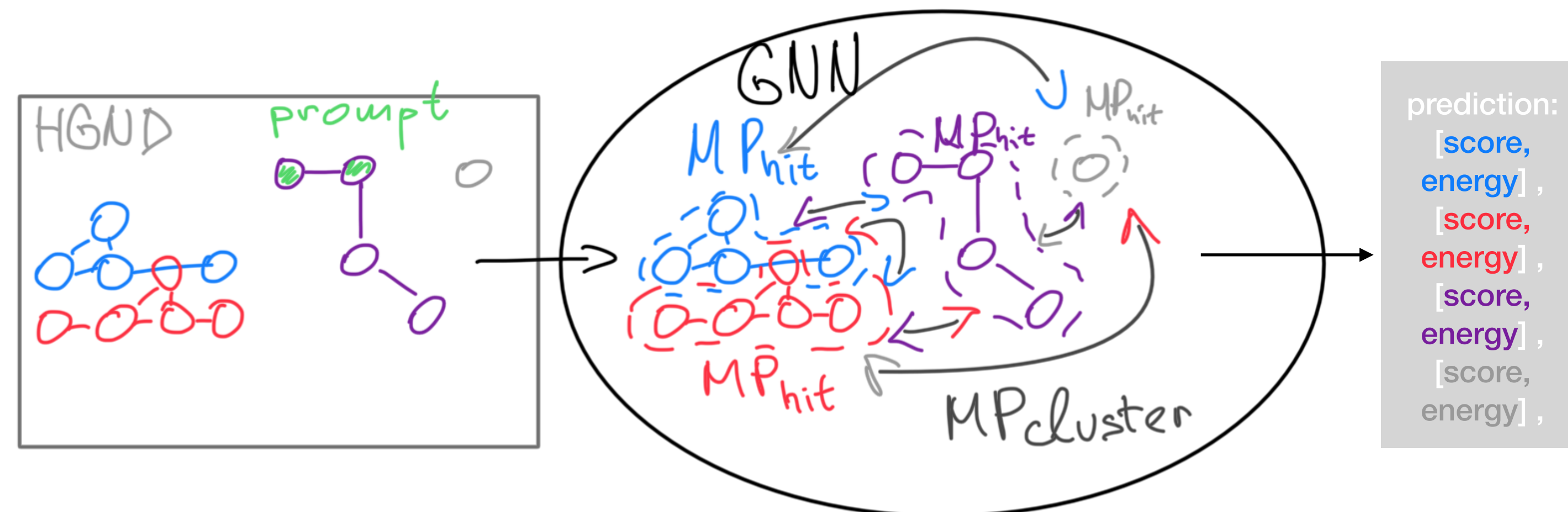
## Loss function

- Binary Cross Entropy for classification
- Mean Squared Error for energy regression

$$Loss = BCE_{cluster} + MSE_{cluster}$$

## Heterogeneous GNN architecture

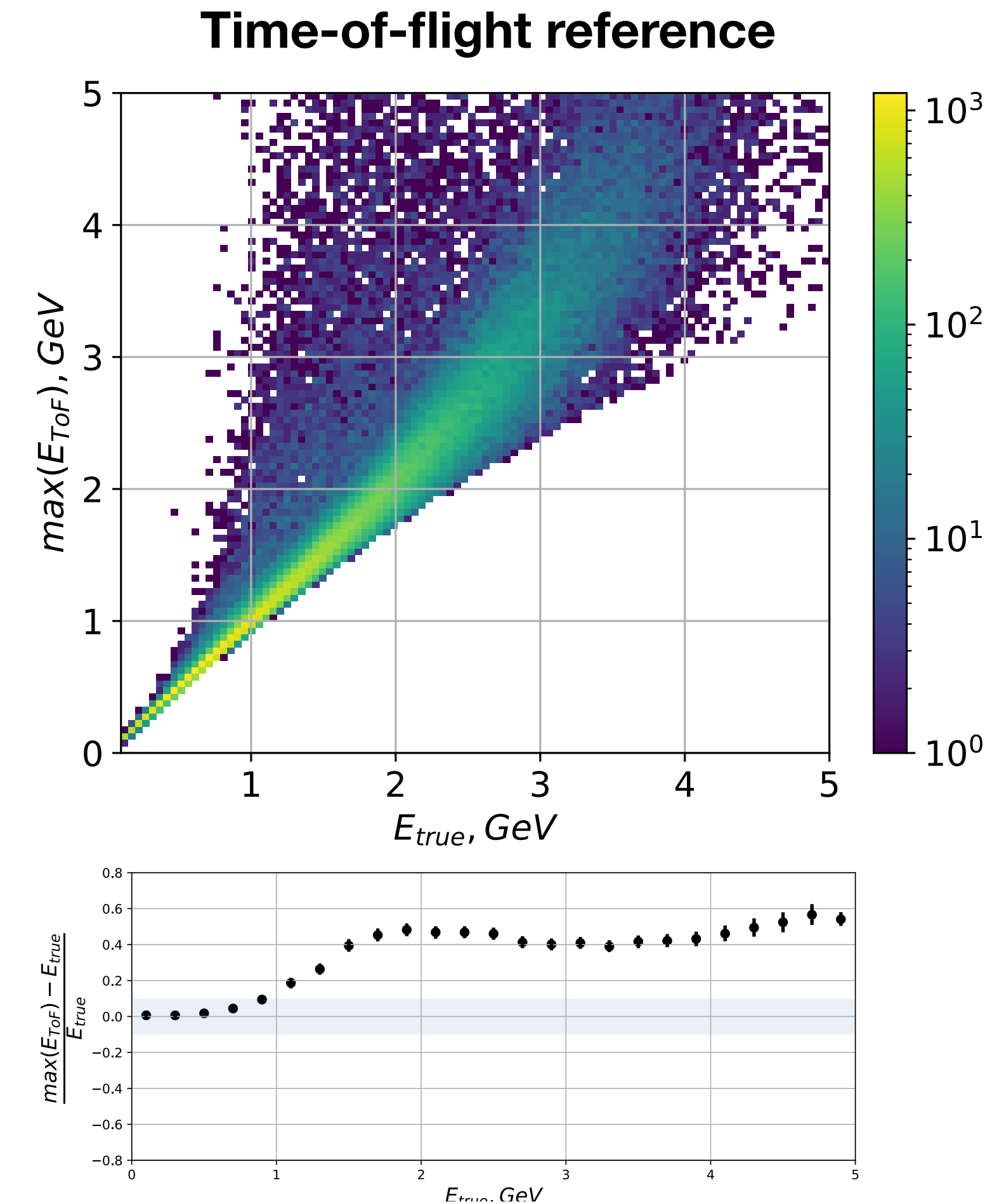
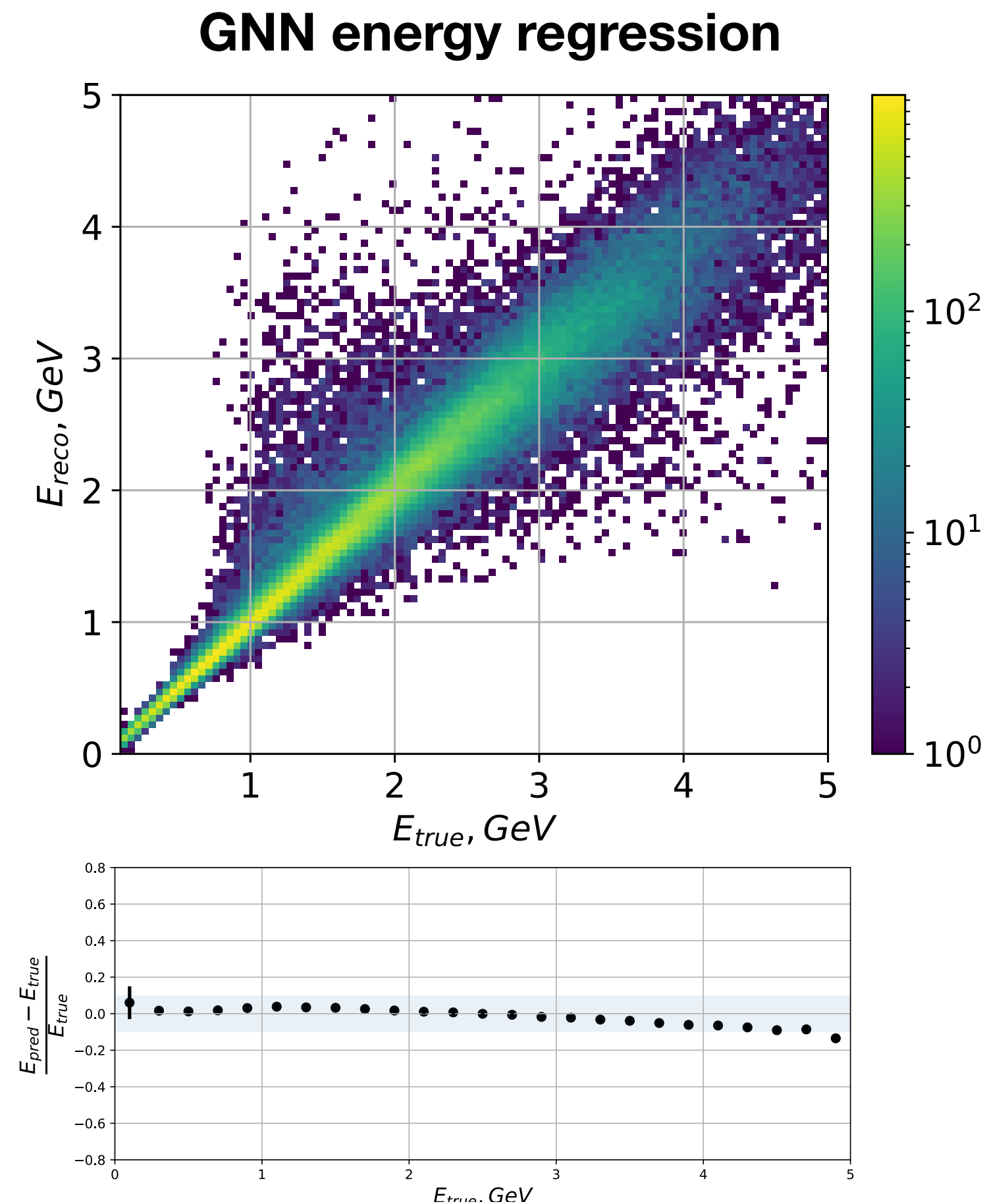
- $MP_{hit}$ . EdgeConv+GraphSage layers *hit*  $\rightarrow$  *hit* within clusters
- GraphConv layer to aggregate *hit nodes*  $\rightarrow$  *virtual cluster node*
- $MP_{cluster}$ . FC EdgeConv layer. *cluster*  $\rightarrow$  *cluster*
- Cluster output: **class score, predicted energy**



PyTorch Geometric library

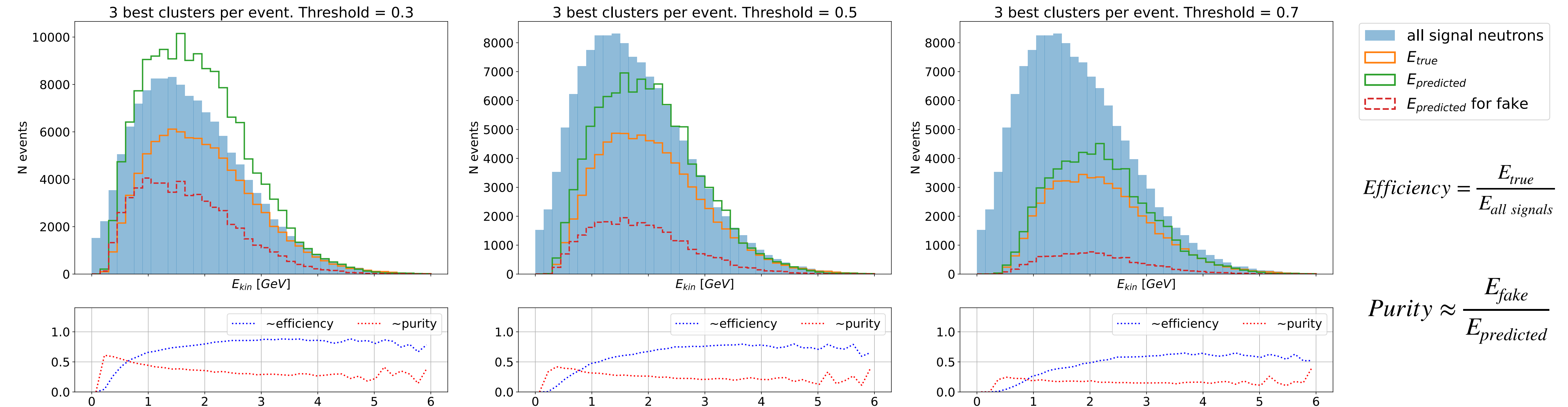
# Cluster Reconstruction Performance

- Overall good cluster classification performance. **ROCAUC $\approx 0.96$**
- **Energy resolution  $\approx 13\%$**  — estimated on integrated relative error for true neutron clusters
  - **Linearity within 10%** for the most part of energy spectrum. Model compensates ToF overestimation



# Neutron Energy Spectra

## Examples of resulting neutron energy spectra

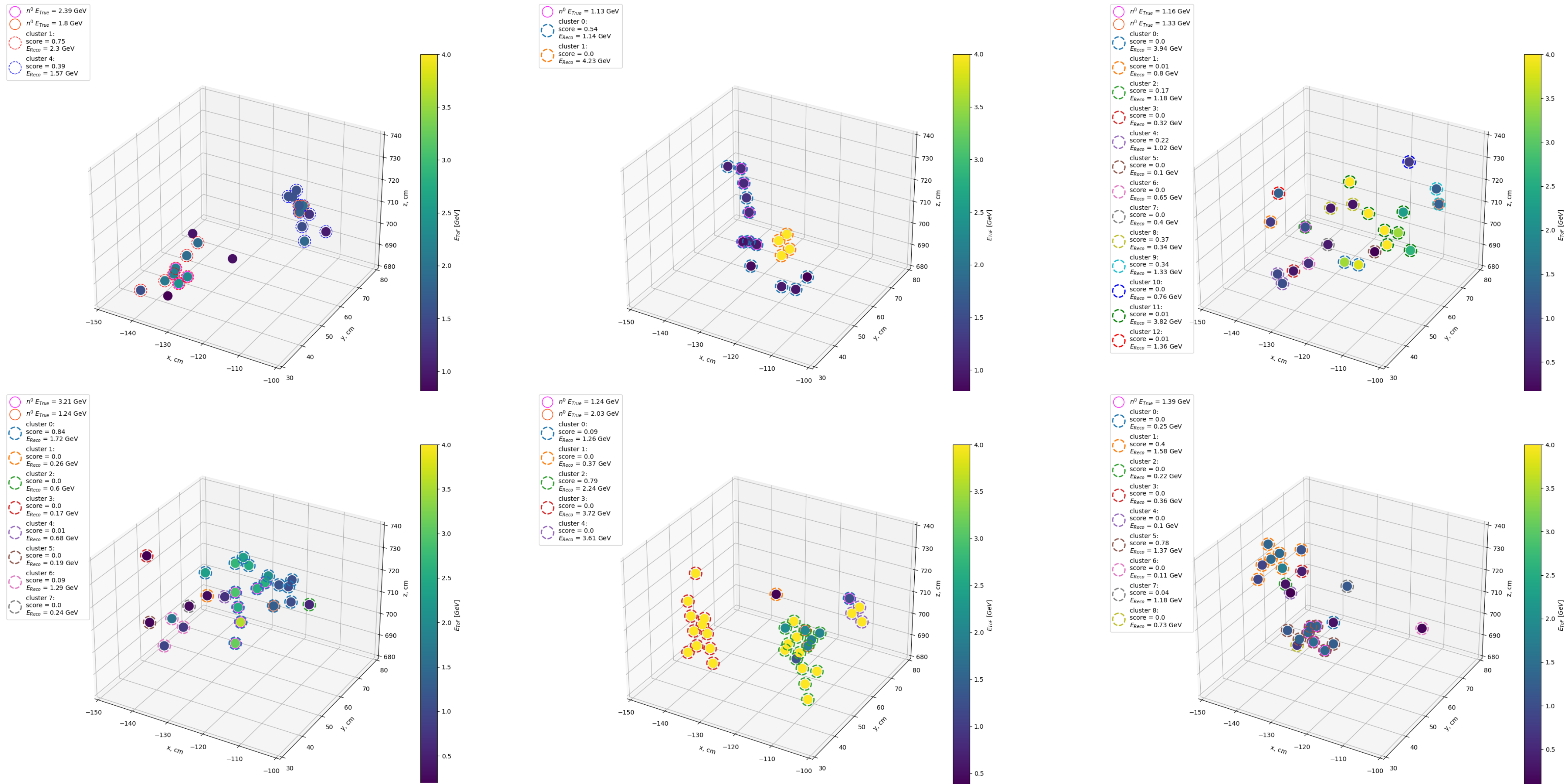


- Energy dependent reconstruction performance
- Trade between purity and efficiency
- Optimal reconstruction scenario will be optimised on end-to-end physics performance simulation

# Summary & Outlook

- Graph Neural Network-based neutron reconstruction algorithm in the highly granular time-of-flight detector is presented
- Further steps for GNN model development:
  - Implementation of differentiable clustering
  - Detailed study of background contributions
  - ➡ Model architecture development
- Final physics performance and optimal reconstruction procedure will be defined using parametrised simulations
  - ➡ Generative model is under development

# Event Displays

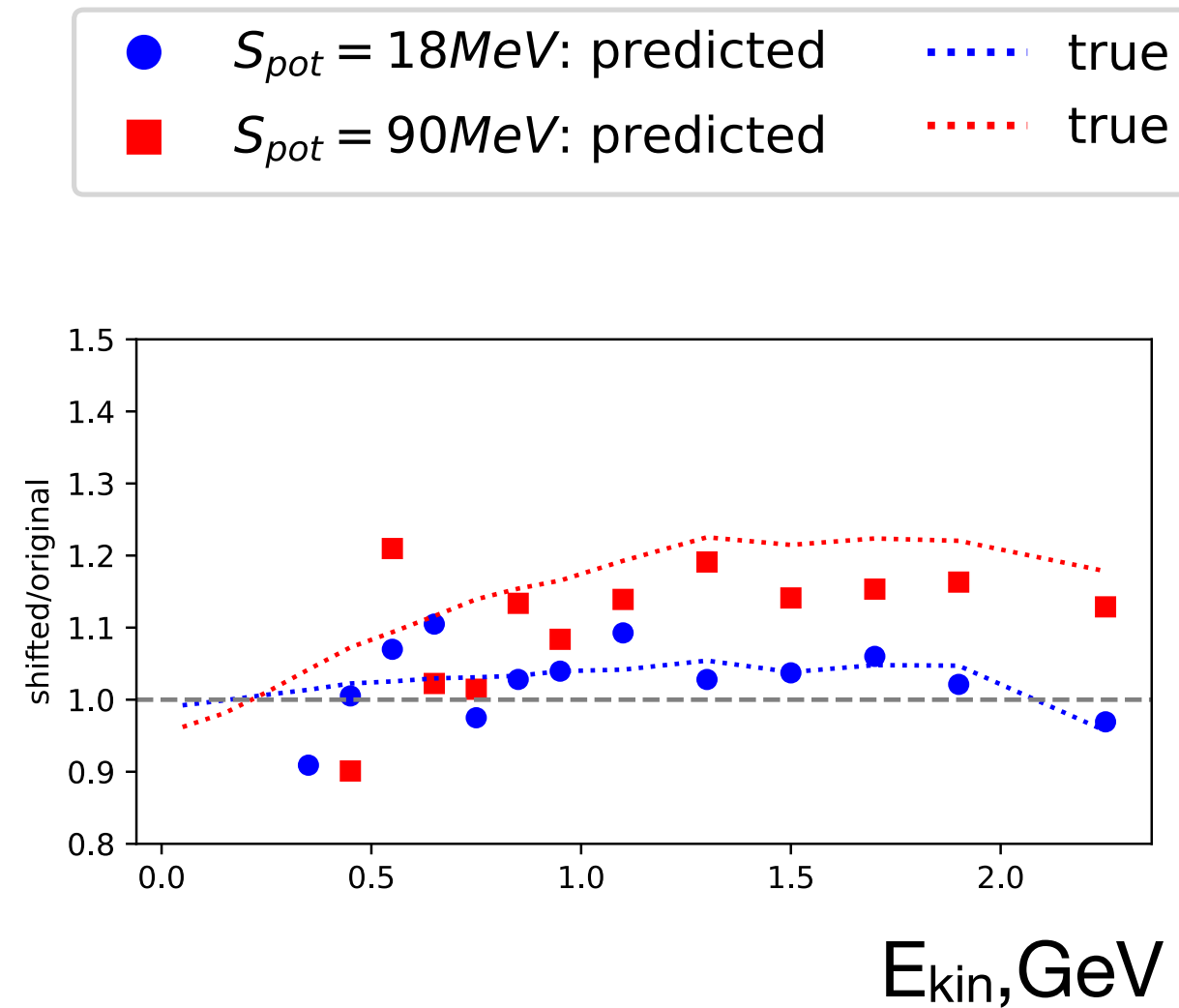
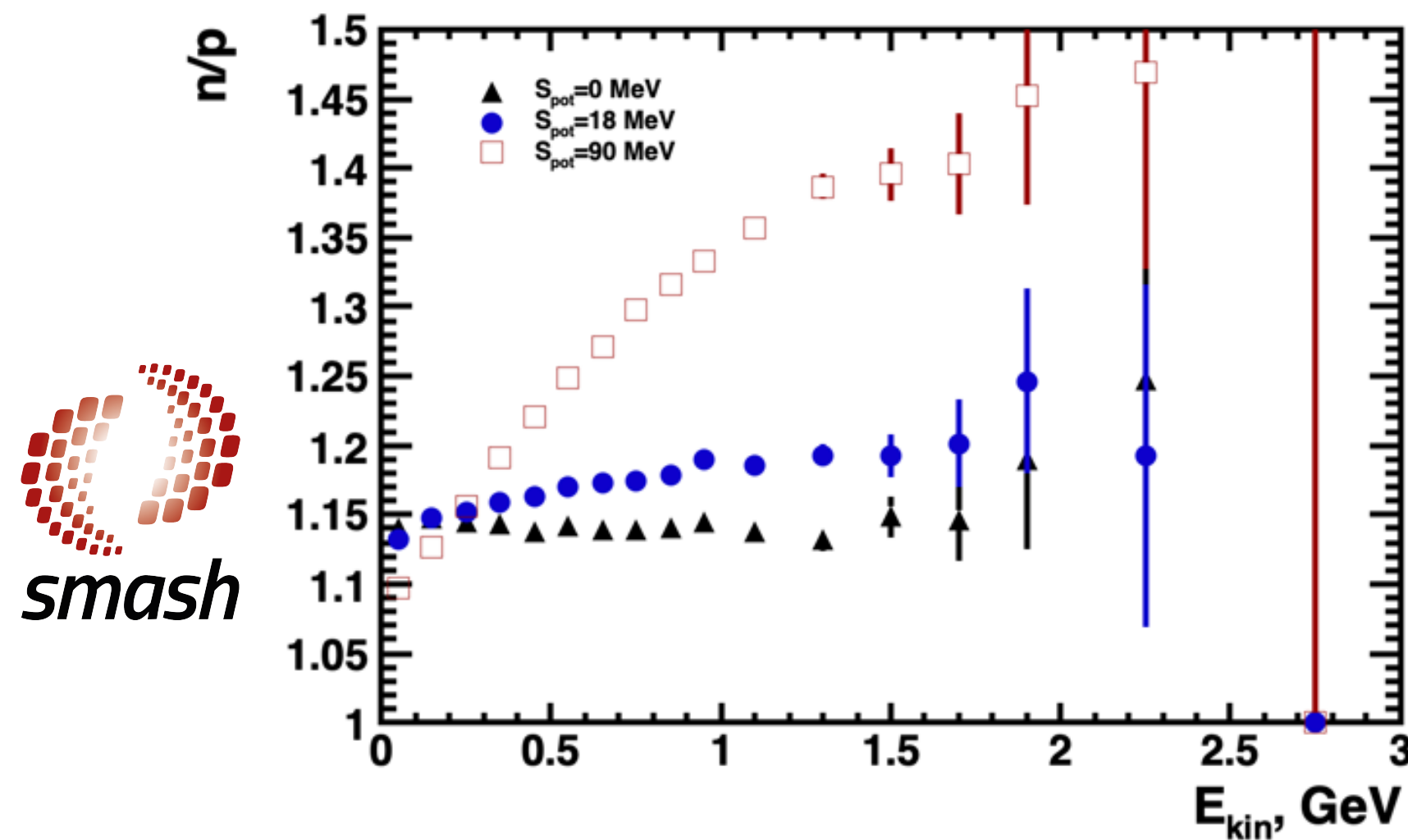


# Physics performance toy-test

Resample test HGND dataset to get different neutron spectra:

**SMASH simulations Xe+Cs @ 3.8A GeV:**  
500k events for 3 symmetry potential ( $S_{\text{pot}}$ ) values

**Neutron to proton ratio vs  $E_{\text{kin}}$ .**  
**All reaction particles.**  
Centrality selection:  $|y| < 0.5$

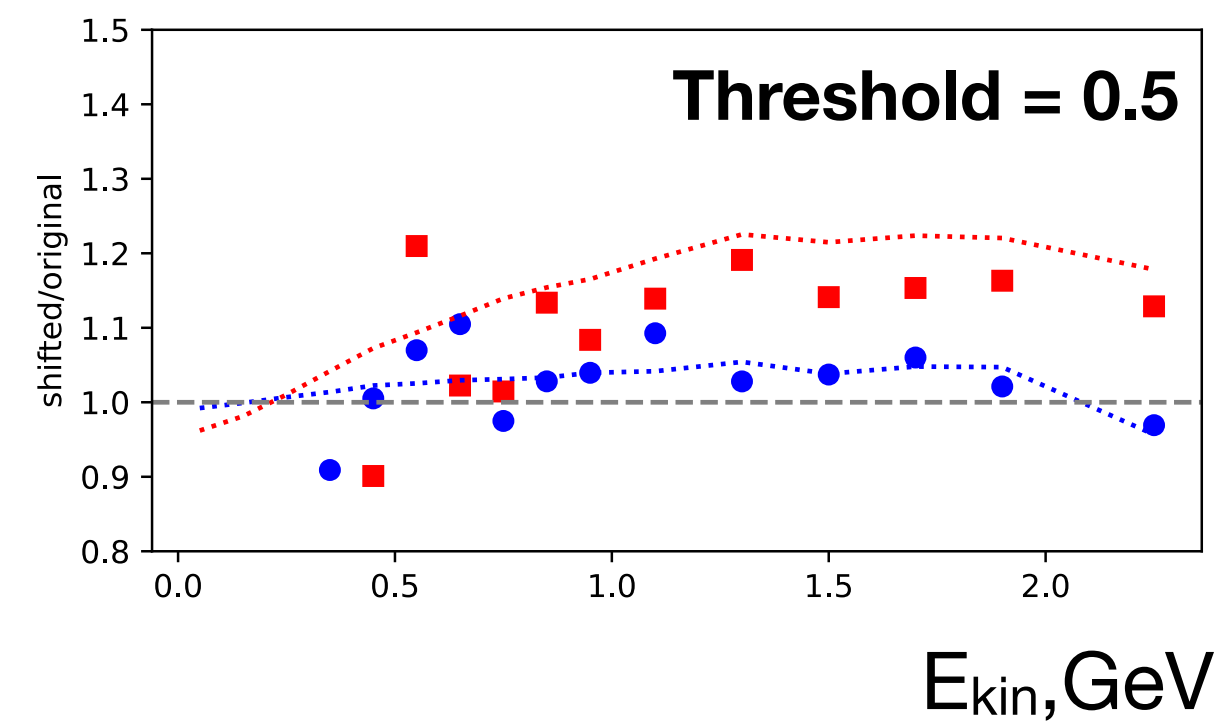
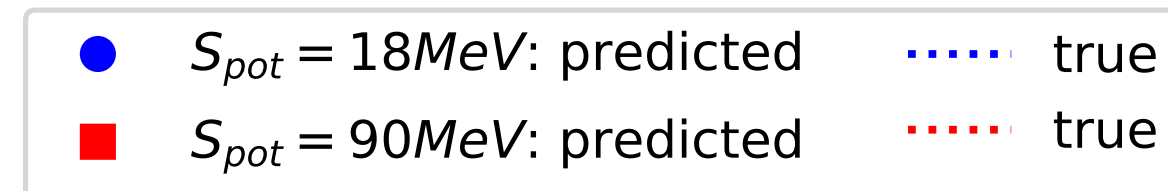
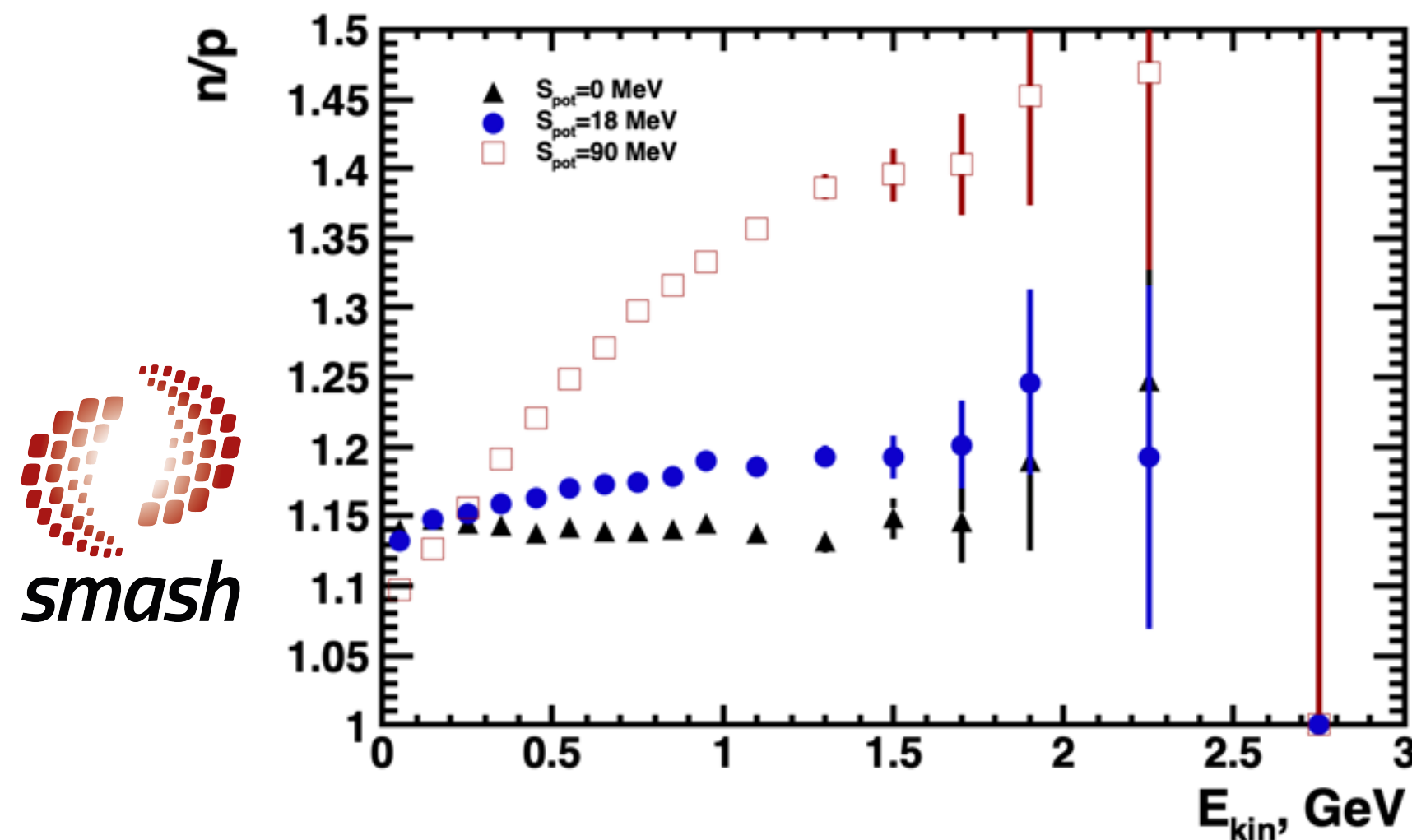


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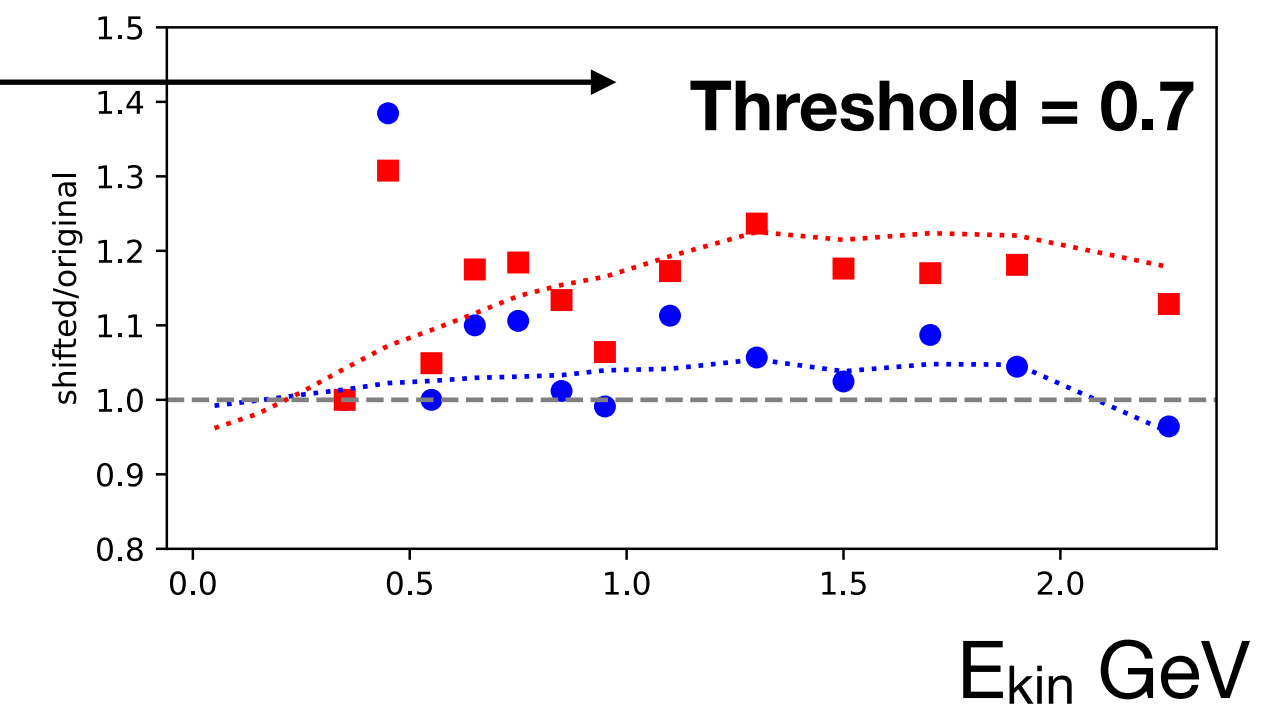
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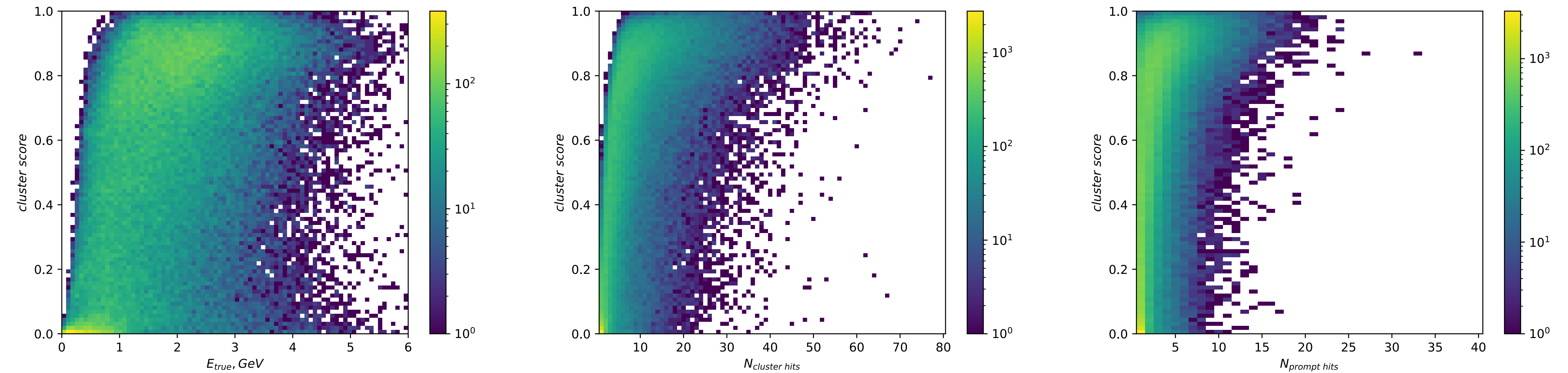


more strict neutron selection

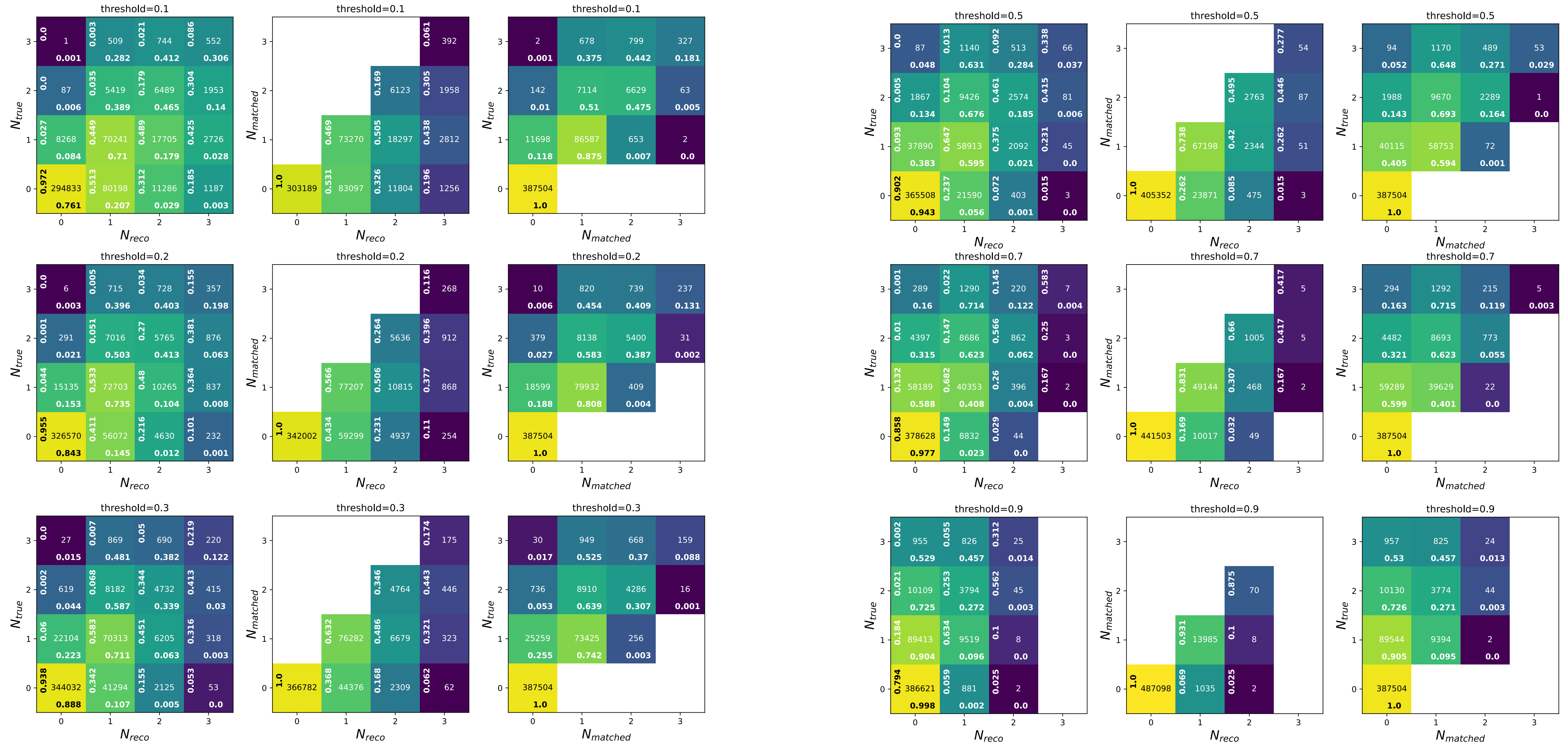


- Qualitatively, it's possible to separate different symmetry potential at  $\sim 1$  GeV+ with relatively strict selection criteria
- Detailed understanding of background contributions is essential

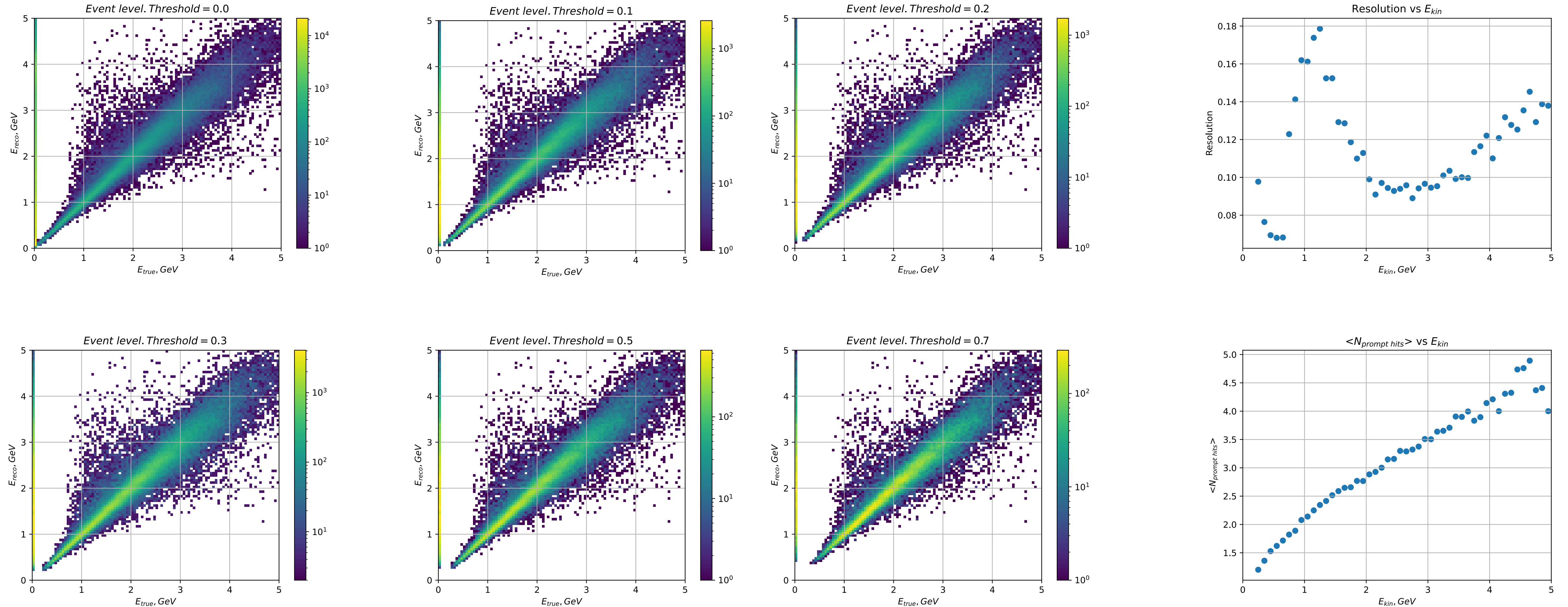
# Score for different clusters



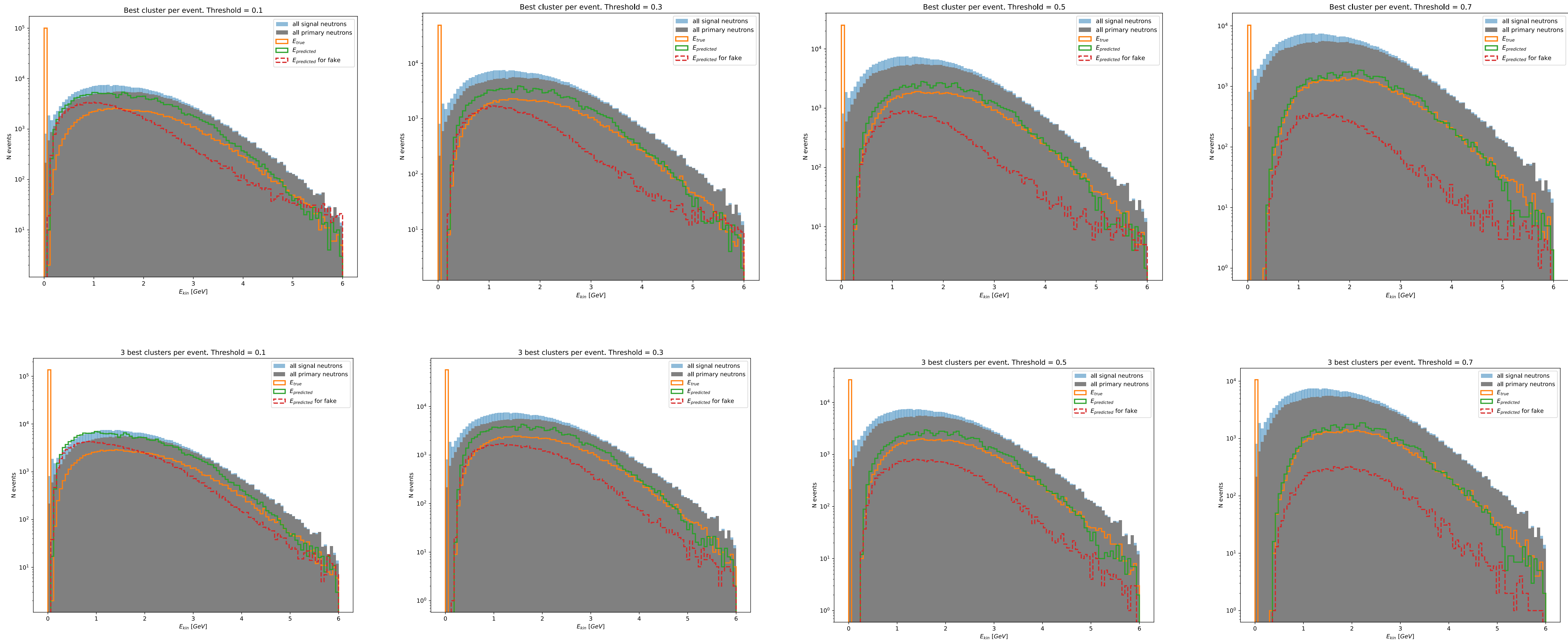
# Multiplicity Reconstruction



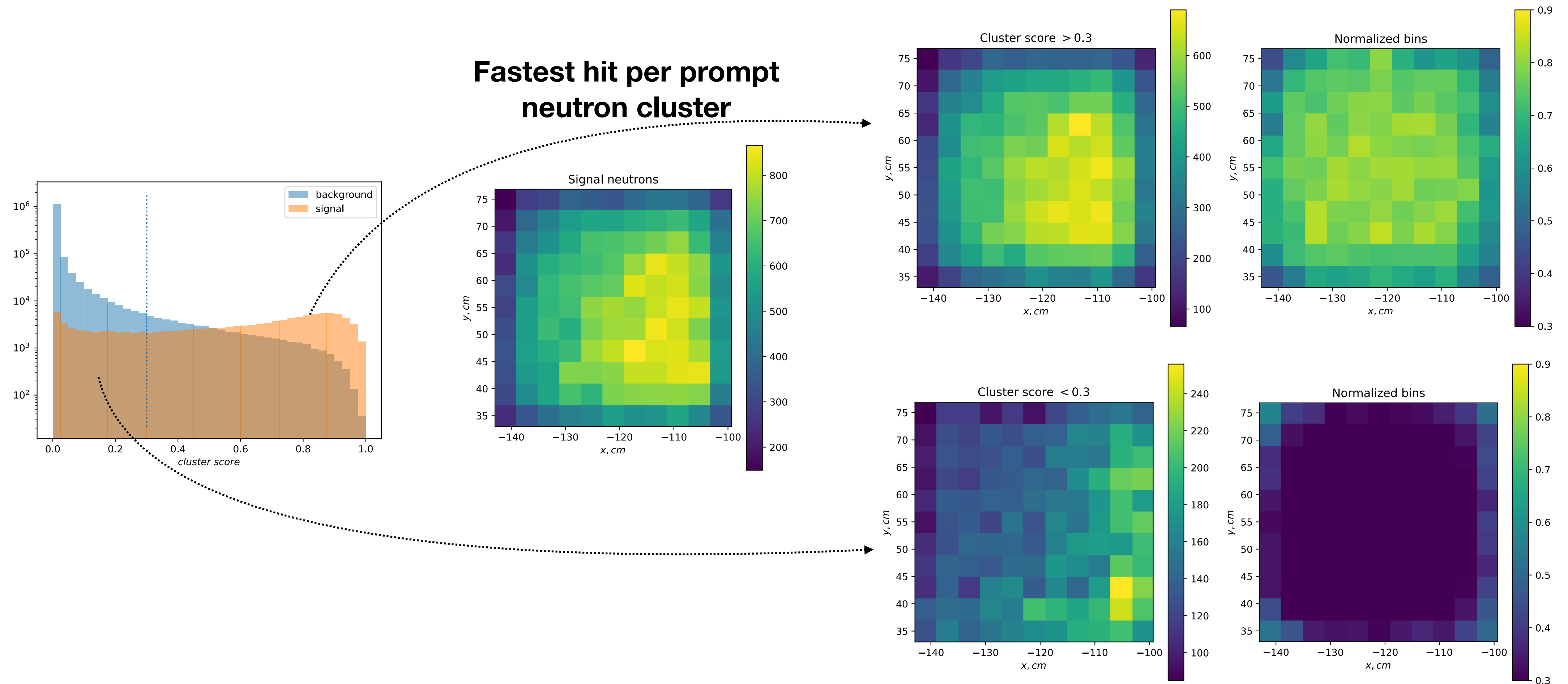
# Energy Reconstruction



# Spectra Reconstruction



# Efficiency in the XY-plane

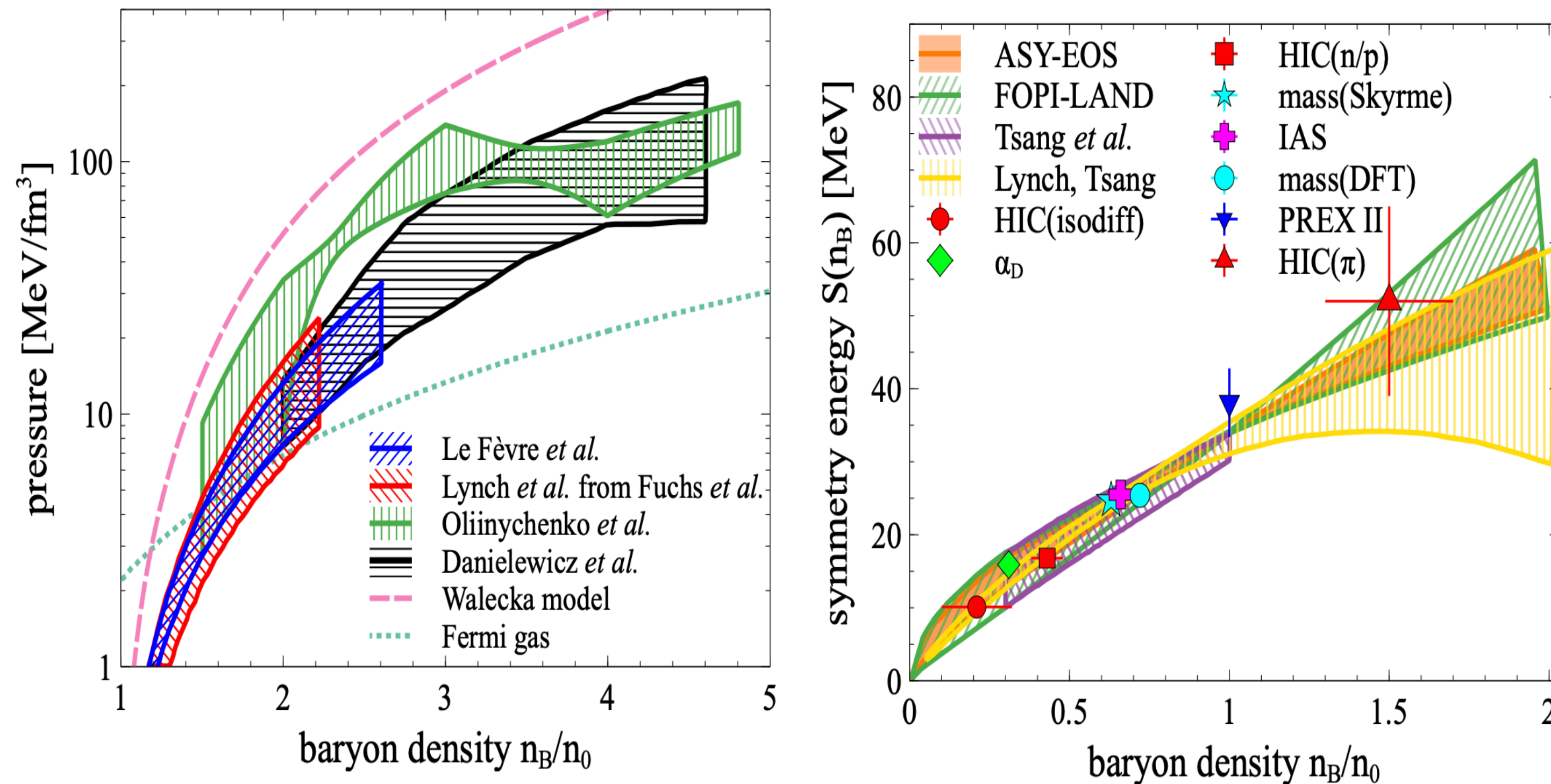


# EOS for high baryon density matter

The binding energy per nucleon:  $E_A(\rho, \delta) = E_A(\rho, 0) + E_{sym}(\rho)\delta^2 + O(\delta^4)$

Symmetric matter

Symmetry energy



$\delta = (\rho_n - \rho_p)/\rho$  - Isospin asymmetry

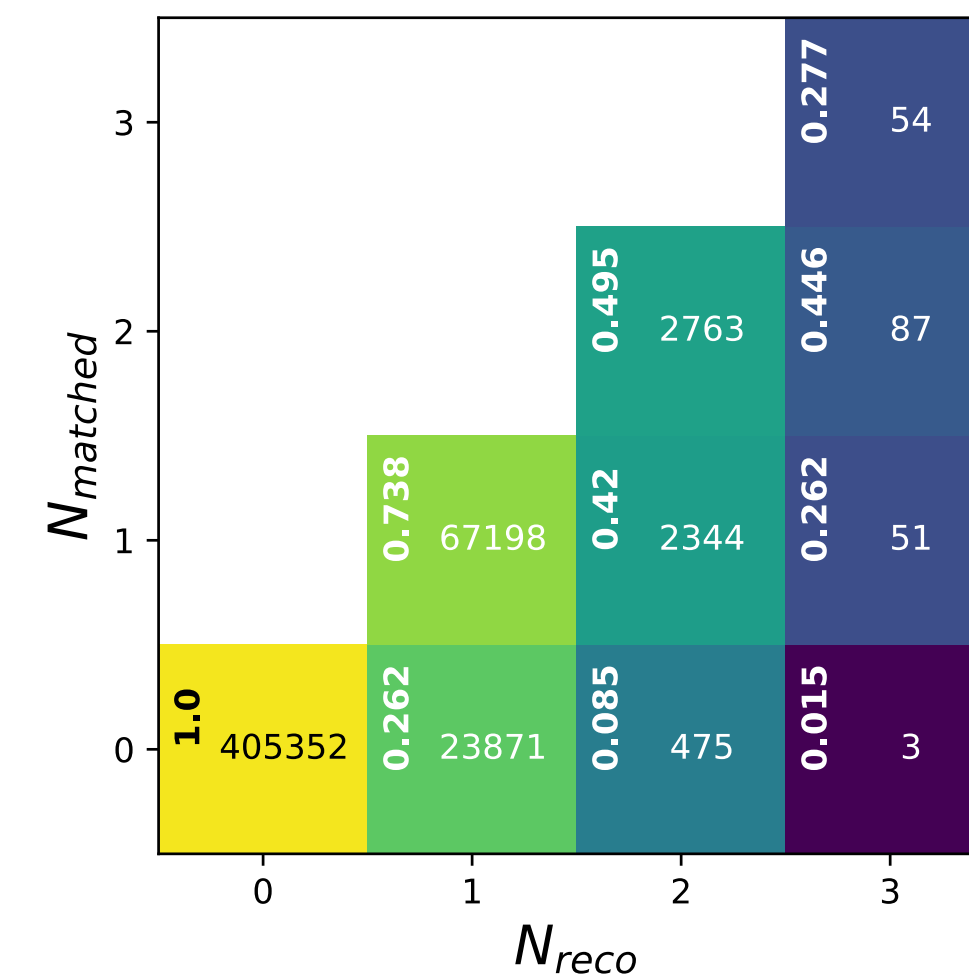
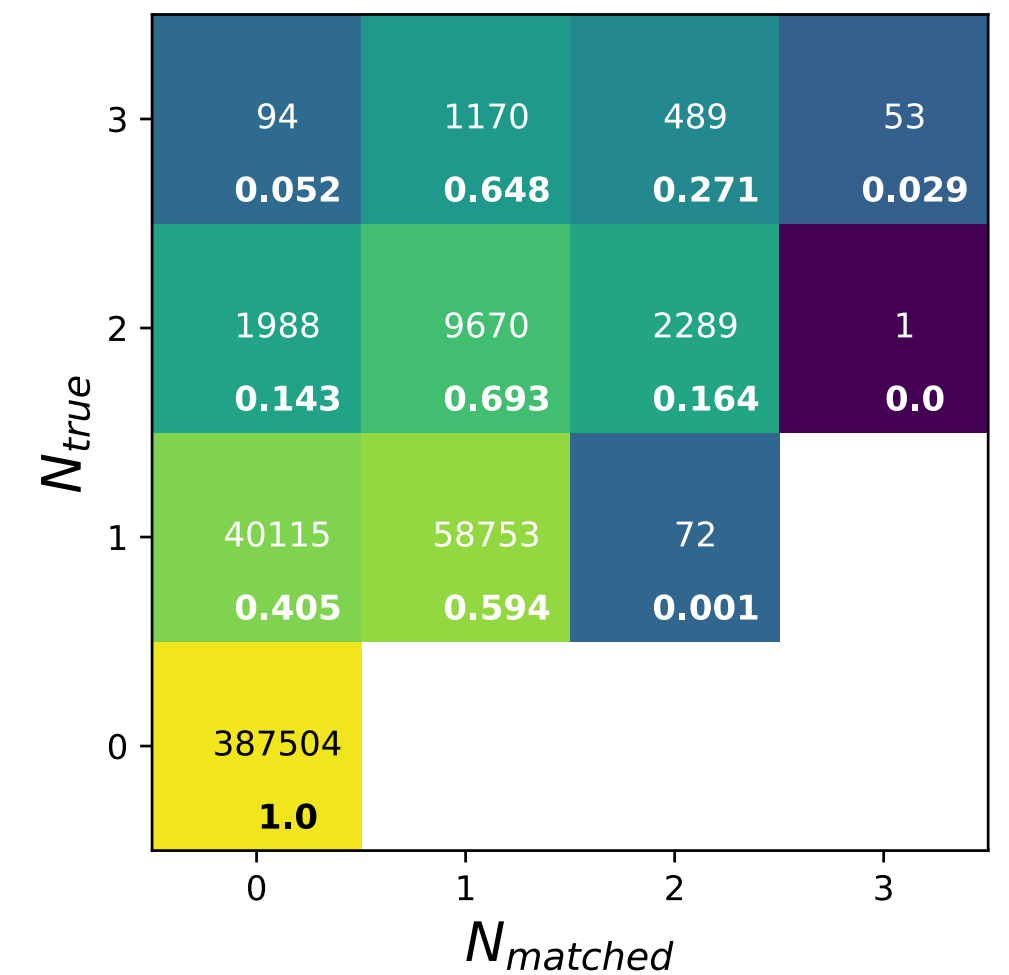
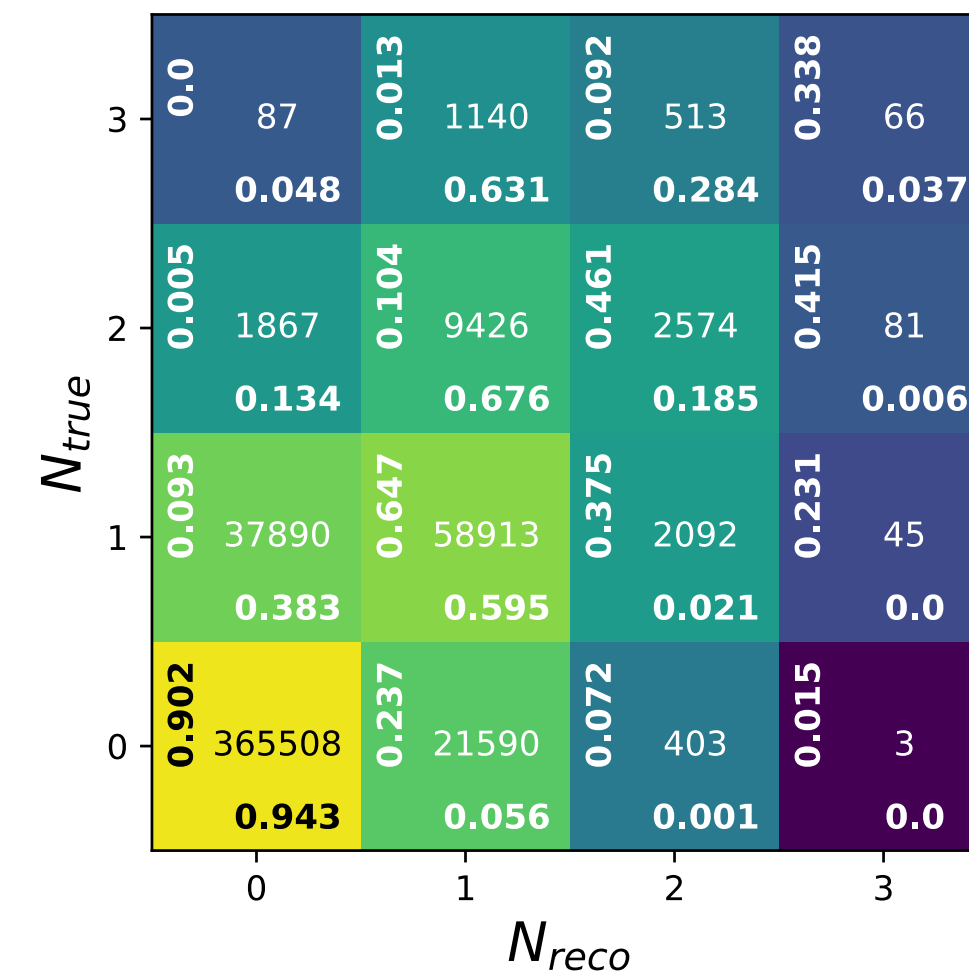
- Symmetric matter is extensively studied
  - **Symmetry energy** contribution lacks experimental data at energies above 800A MeV
    - Neutron-rich matter like a neutron star requires measurement of symmetric energy parameters
- ➔ reconstruction of **neutron** flow and yields

A. Sorensen *et. al.*, Prog.Part.Nucl.Phys. 134 (2024) 104080

# Multiplicity Reconstruction

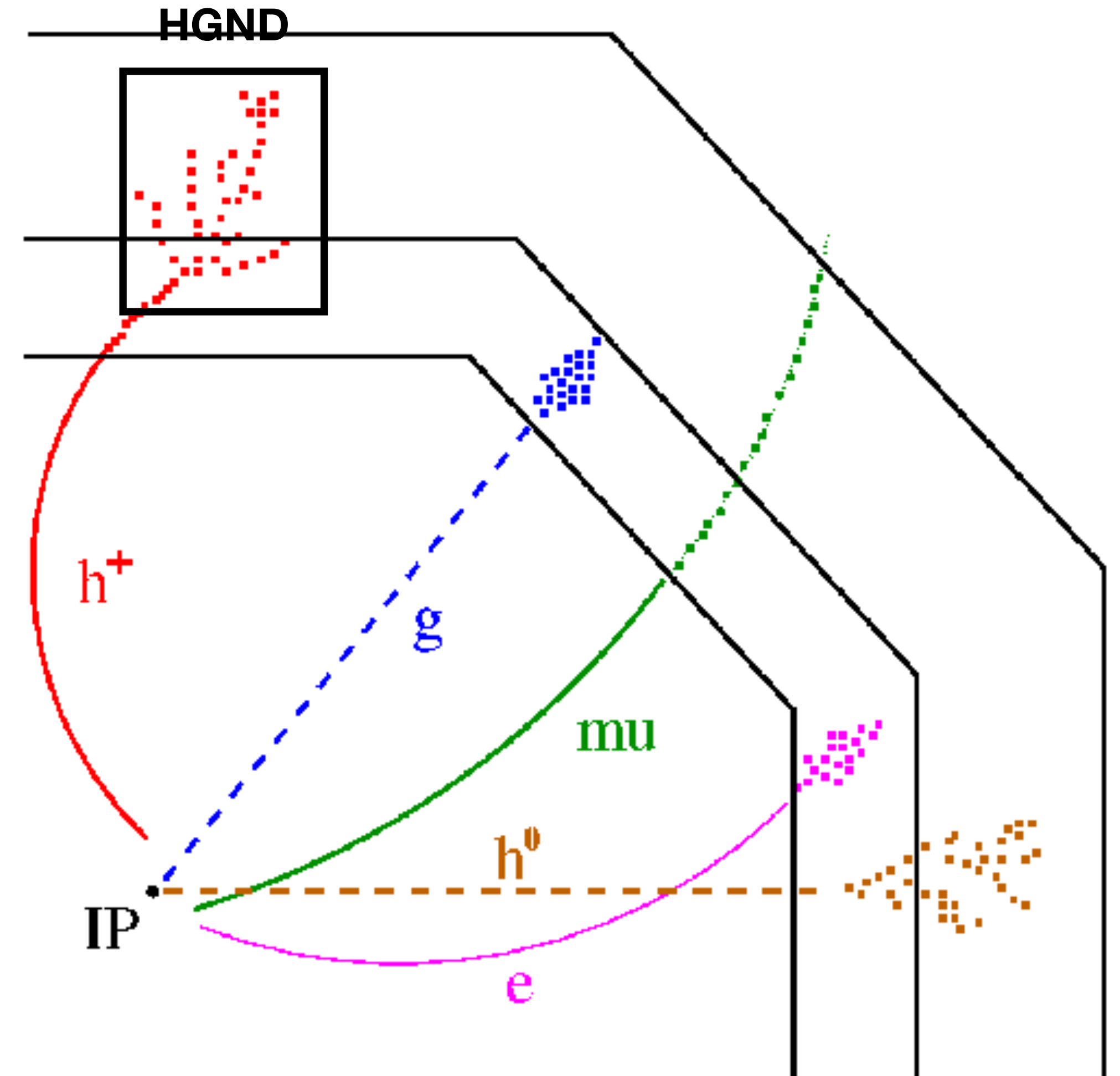
- Test dataset
  - 502198 events
- Selection:
  - $E_{\text{true}} > 0.1 \text{ GeV}$
  - $E_{\text{reco}} > 0.1 \text{ GeV}$
- 4 multiplicity classes:
  - [0, 1, 2, 3 and more]
- Fixed cluster score threshold = 0.5
- horizontal normalisation is related to efficiency
  - efficiency decreases for higher true multiplicities and higher score threshold
- vertical normalisation is related to purity
  - high score threshold allows to separate up to 3 'good' neutron clusters

Matched neutron - reconstructed cluster corresponds to MC-truth neutron cluster.



# Tracking Outlook

- BM@N has a dedicated tracking system to reconstruct charged particles
- Tracks may be projected to the HGND upstream surface
- ➡ Additional source of information to reject clusters from charged particles

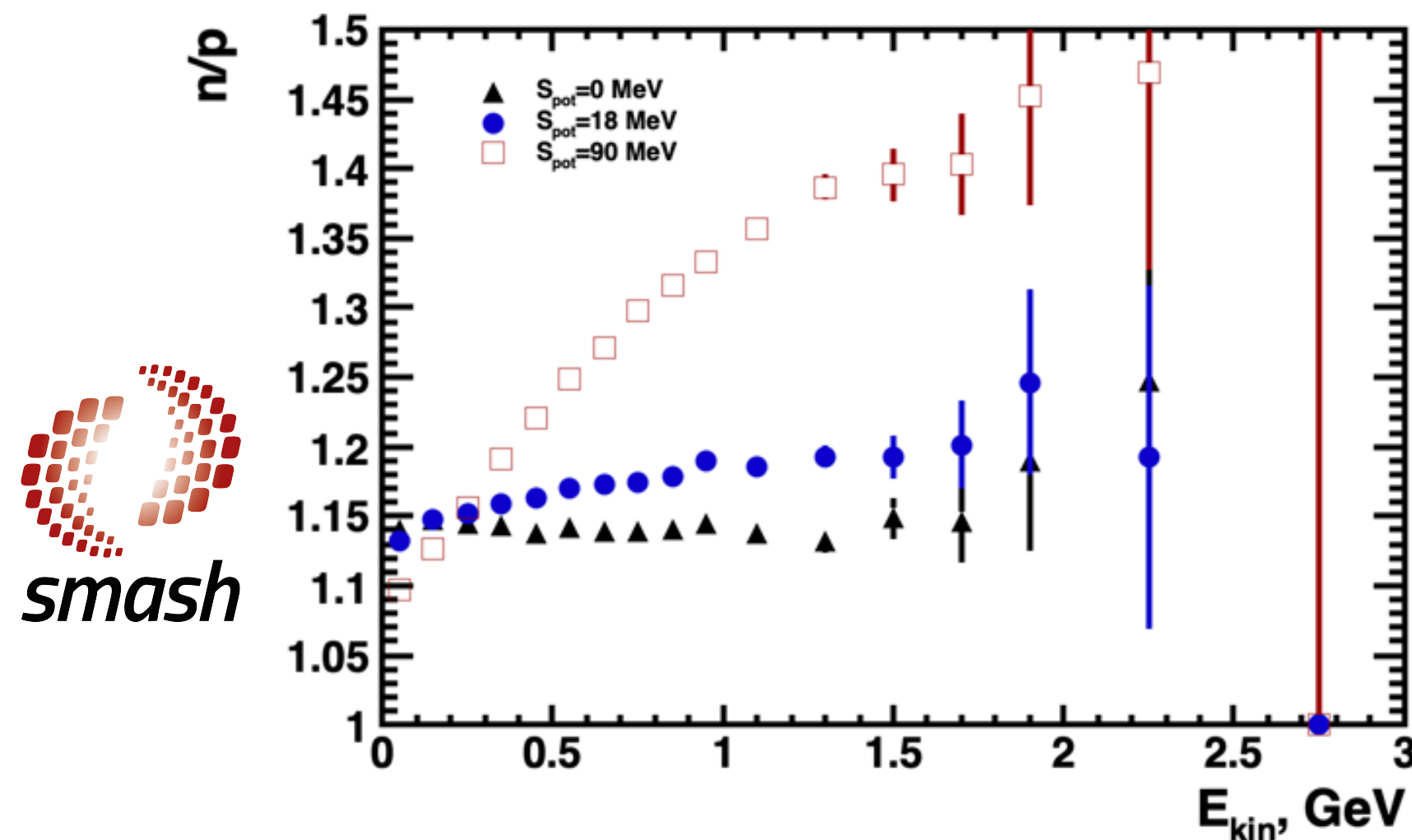


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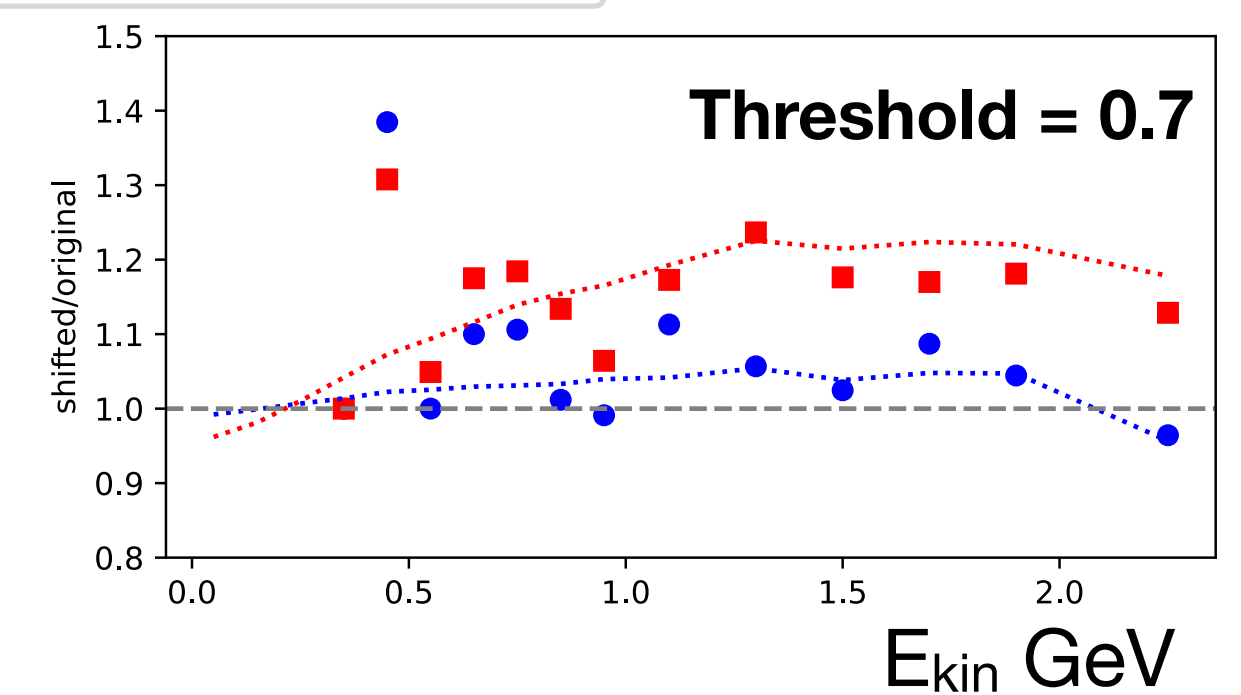
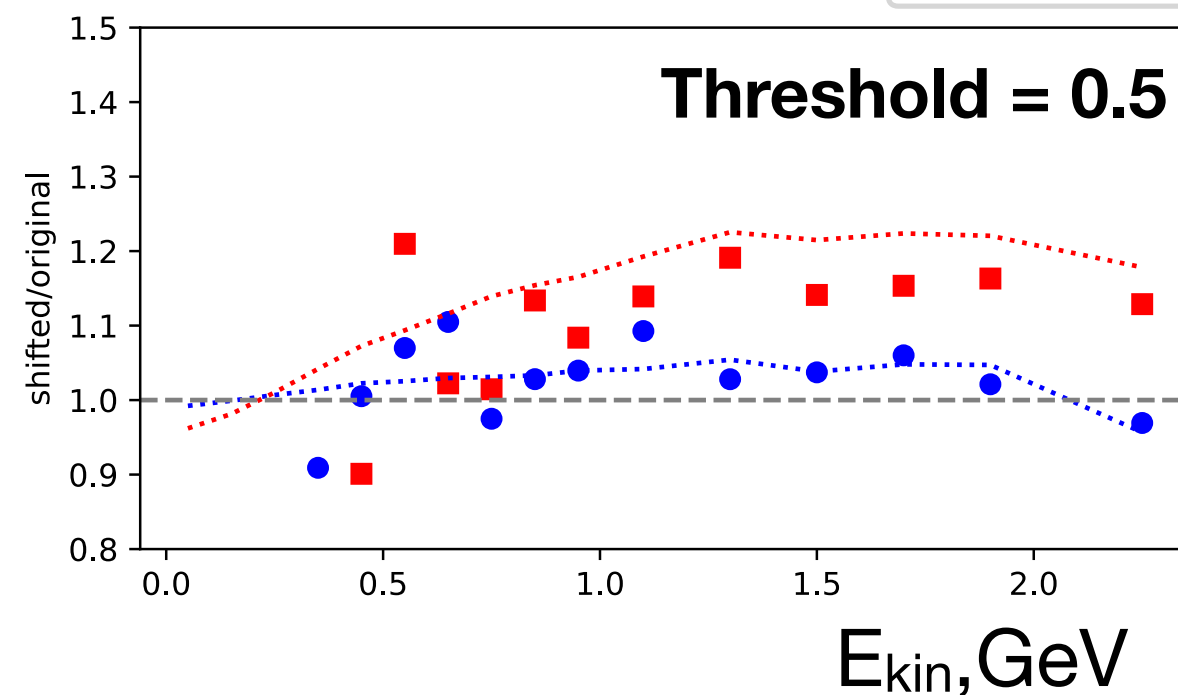
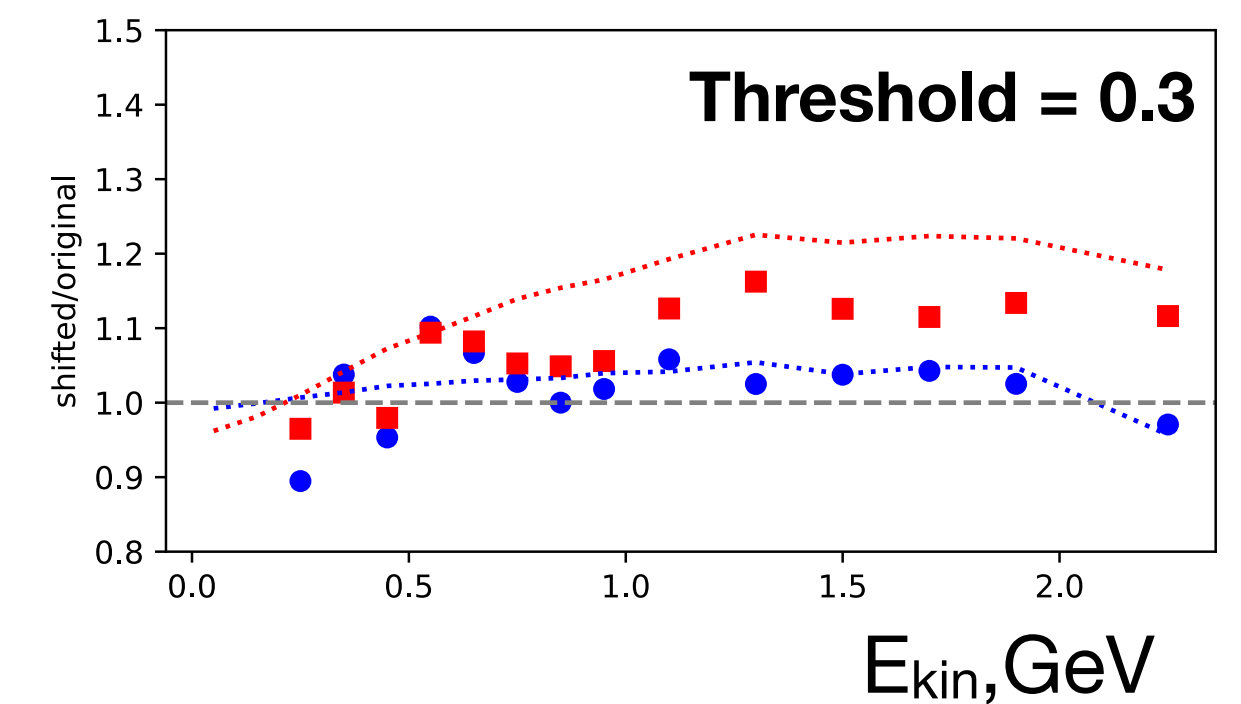
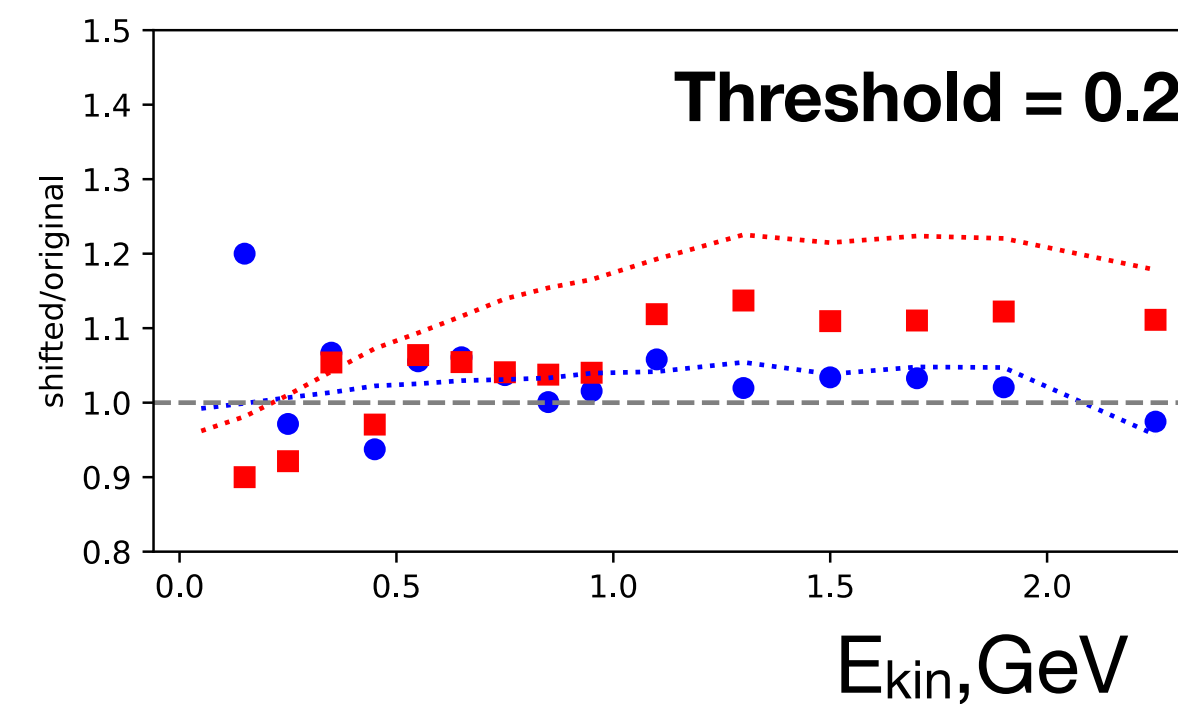
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- Detailed understanding of background contributions is essential

# Event Level Performance

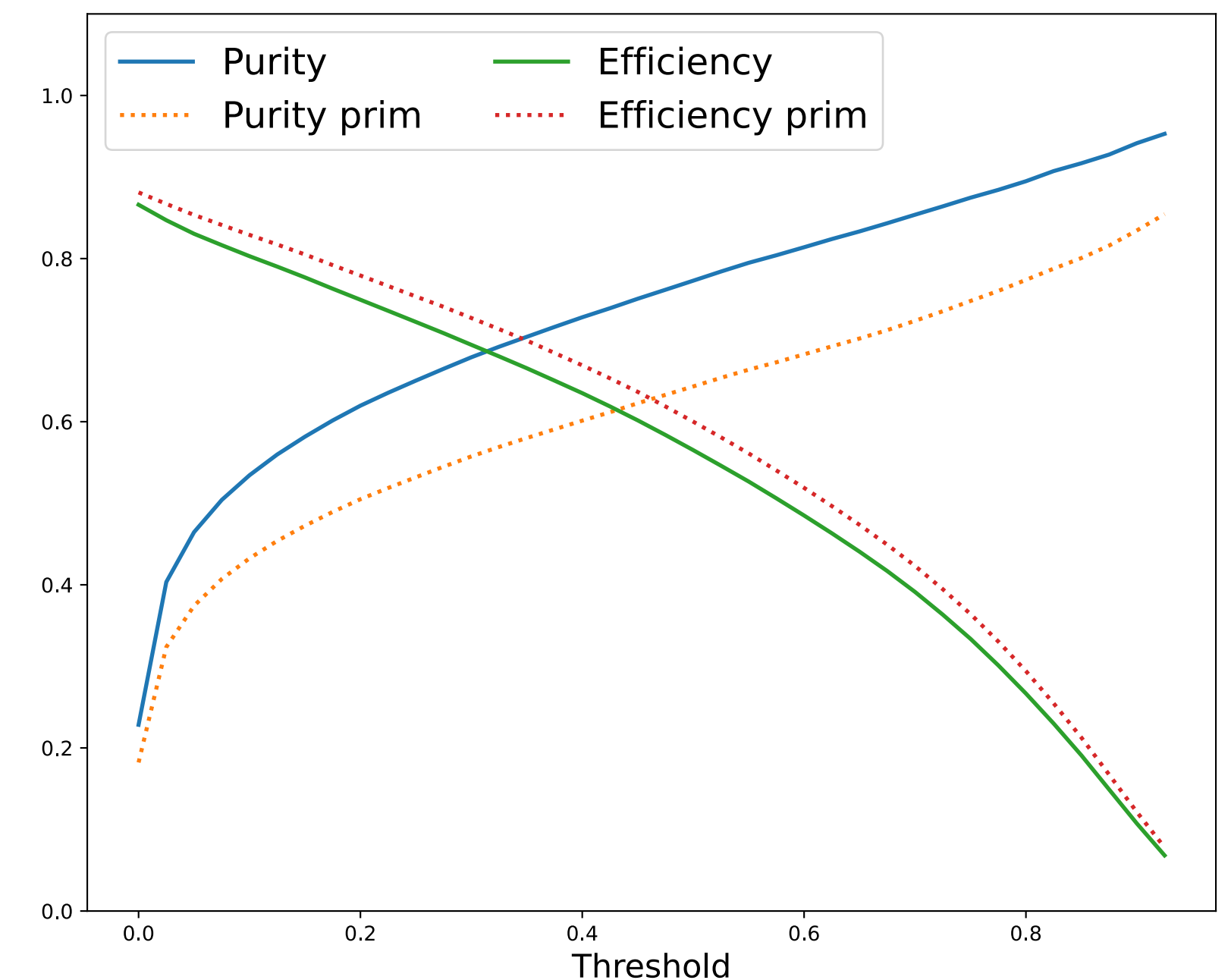
## Single neutron reconstruction approach:

- Select best cluster in event by cluster score
- Varying threshold for event score and calculate neutron reconstruction efficiency and purity

$$Purity = \frac{N_{reco\ true}}{N_{reco\ all}}$$

$$Efficiency = \frac{N_{reco\ true}}{N_{neutrons}}$$

## Event classification performance vs score threshold



- At selected threshold 0.5 Efficiency  $\approx$  0.57, Purity  $\approx$  0.77

# Motivation

Measurements of neutron flow and yields require **reconstruction of neutrons**

Neutron reconstruction task:

- **Identify neutrons** produced in reaction in presence of background
  - ➡ use of **high granularity**
- Reconstruct neutron kinematics:
  - Kinetic energy — **time-of-flight** (ToF) method
- Multi-parameter task  $\Rightarrow$  may benefit from **ML-based methods**